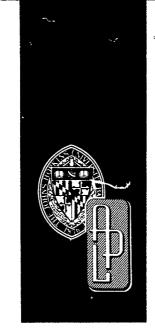
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Technical Memorandum

A SIMPLIFIED STREAMLINE SWALLOWING PROCEDURE FOR THE WINDWARD MERIDIAN OF **AXISYMMETRIC BLUNT BODIES**

J. B. KOUROUPIS

THE JOHNS HOPKINS UNIVERSITY . APPLIED PHYSICS LABORATORY

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6c. ADDRESS (City, State, and ZIP Code)		<u> </u>	7b ADDRESS (City,	, State, and ZIP Code)		
Johns Hopkins Road Laurel, Maryland 20707			Johns Hopkir Laurel, Mary			
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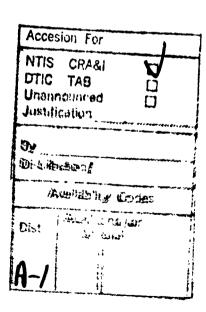
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ABSTRACT

A relatively simple procedure has been developed to include variable boundary layer edge entropy in an inviscid flow solution on the windward ray of axisymmetric blunt bodies. Variable boundary layer edge entropy is significant downstream of the nose region on blunt bodies due to entropy gradients along the curved bow shock. Laminar and turbulent boundary layer growth models are used in a mass balancing technique to account for the effects of entropy gradients produced at the bow shock. The solution is driven by the inviscid surface pressure distribution, mass flow within the boundary layer, and bow shock shape. The code takes about 10 min/case to run on an IBM AT personal computer. Heat transfer comparisons to experimental data and other heating rate codes are favorable. The method is accurate from $M_{\infty}=2.8$ to 15 for cones with flow incidence angles up to 25°.





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1.0 INTRODUCTION

Predicting aerothermal heating along the windward meridian of axisymmetric blunt bodies in supersonic and hypersonic flight is a common engineering problem. A simple, fast, and inexpensive way to calculate heating is to correlate boundary layer (BL) edge conditions to a heat transfer coefficient. Inherent to the method is determining the flow properties at the BL edge through the solution of greatly simplified forms of the Navier-Stokes equations. Ever present is the drive toward simpler methods that sacrifice as little accuracy as possible when compared to complete Navier-Stokes solutions to the body surface.

The classical (and simplest) approach for calculating BL edge conditions is to neglect coupling between the inviscid flow region and the BL, thereby treating the BL edge as an isentropic surface. The properties along the BL edge are found by following the stagnation streamline as it passes through the normal bow shock and then by assuming an isentropic expansion from the stagnation point around the body surface. The method requires only the pressure distribution and normal shock entropy for a complete thermodynamic definition of the BL edge. Currently, a computer code named ABBOHT (Axisymmetric Blunt Body Heat Transfer) is used to calculate cold (isothermal) wall heat transfer to the windward ray of blunted bodies in just such a manner.

In 1953 Ferri and Libby 1,2 found that entropy gradients induced by bow shock curvature around a blunted body produce a coupling effect between the inviscid region and the BL that can invalidate the classical solu-

tion. First, the entropy along the BL edge will continuously vary aft of the nose region; second, the velocity gradient at the predicted BL edge $(\partial u/\partial y)$ will not be zero (producing nonsimilar BL growth) as previously assumed. The latter effect is significant when the external stream vorticity is of the same order of magnitude as the average BL vorticity (i.e., low Reynolds no. combined with high Mach no. flow). External flow vorticity effects are small at high Reynolds no. flow and on slender blunted cones (half angles less than 25°). Since that is the flow regime commonly used in ABBOHT, it was desired to upgrade the code to include variable entropy effects while accepting the BL similarity limitations.

Modifications to the classical, first-order approach to include shock curvature effects were investigated from 1960 to 1968 by Zakkay and Krause, Wilson, Rotta and Zakkay, and Murzinov. 3-6 All found the need to account for variable BL entropy through "entropy layer swallowing" or "streamline swallowing." That event occurs as follows: BL growth along a body is caused by mass entrainment of the inviscid external flow with streamlines that have passed through an increasingly oblique portion of the bow shock. Mass entrainment eventually swallows the high-entropy BL from the nose region. Consequently, the BL downstream of the nose region consists of lower entropy streamlines resulting in higher BL velocities and higher heat transfer rates than for the classical method, Low BL velocities and heat transfer at aft body stations in the old version of ABBOHT are documented in Ref. 7.

¹A. Ferri and P. A. Libby, "Note on the Interaction Between the Boundary Layer and the Inviscid Flow," J. Aeronaut. Sci. 21, 120 (1951)

²A. Ferri, "Some Heat Transfer Problems in Hypersonic Flow," in *Aeronautics and Astronautics*, Pergamon Press, New York, pp. 344-377 (1960)

³V. Zakkay and E. Krause, "Boundary Conditions at the Outer Edge of the Boundary Layer on Blunted Conical Bodies," *AIAA J.* 1, 1671-1672 (1963).

⁴R. E. Wilson, "Laminar Boundary Layer Growth at Hypersonic Speeds," J. Spacecr. Rockets 2, 490-496 (1965).

⁵N. R. Rotta and V. Zakkay, "Effects of Nose Bluntness on the Boundary Layer Characteristics of Conical Bodies at Hypersonic Speeds," *Astronaut. Acta* 13, 507-516 (1968).

^{61.} N. Murzinov, "Laminar Boundary Layer on Blunt Bodies, Allowing for Vorticity of the External Stream," NASA TT F-11007 (Jun 1966).

⁷J. B. Kouroupis, "Cc.nparison of Aerodynamic Heating Between Sharp and Blunt Bodies," JHU/APL BBE/EM-5292 (12 Mar 1986)

2.0 STREAMLINE SWALLOWING METHODS

2.1 MASS BALANCING

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Two simplified (first-order) approaches have been developed to account for entropy layer swallowing in an inviscid code. The first is called mass balancing, whereby the mass flow in the BL at the station of interest is matched with the mass flow in a free-stream cylinder of appropriate radius (y_{sh}) as shown in Fig. 1, which is based on a figure in Ref. 8. The value of y_{sh} is defined

$$y_{sh} = \frac{\dot{m}}{\sqrt{\pi \rho_{\infty} u_{\infty}}}$$

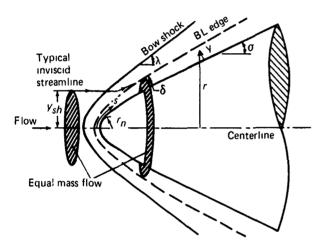


Figure 1 Streamline swallowing on a blunted body.

The bow shock angle at y_{sh} is then used to calculate the entropy behind the shock, which is used with the inviscid surface pressure to determine BL edge conditions. Thus, the bow shock shape, inviscid pressure distribution, and BL mass flow are required for the solution of the above equation.

In 1970-71 Mayne, Adams, and Dyer^{8,9} built on the work done by Patankar and Spalding¹⁰ to develop

heat transfer codes that use mass balancing to account for streamline swallowing for both laminar and turbulent BL flow. Here, BL equations are expressed in a normalized Von Mises coordinate system and are solved using an implicit, finite-difference marching technique. BL mass flow is readily derived from that solution. A Method of Characteristics solution is used for the inviscid region to calculate bow shock shape and surface pressure. Mayne's laminar method accounts for non-similar BL growth, but the turbulent method does not.

In 1972 Price and Harris¹¹ used a technique similar to Mayne's but solved the *nonsimilar* BL equations for laminar, transitional, and turbulent flow. Thus, all three BL flow regimes can account for the effects of vorticity interaction. As with Mayne's method, an inviscid flow solution from the bow shock to the body surface was added to define the surface pressure distribution and bow shock shape, thereby allowing the inclusion of mass balancing. The program was revised in 1982¹² to increase its accuracy and computational efficiency.

In 1974 DeJarnette and Hamilton 13 devised a different approach for using mass balancing to account for streamline swallowing. First, a modified Newtonian surface pressure distribution is calculated over the body. Inviscid surface streamlings are then defined using Euler's equation along with two stream functions. This is an inverse method, where the bow shock shape can be found from stream function values. Those values also define the BL mass flow rate, which is matched to freestream flow rates. The method is iterative, does not account for nonsimilar BL growth, and is generally less accurate than Mayne's method; it is, however, simpler and can be extended easily to three-dimensional geometries. Modifications to make the basic technique noniterative were made by Fivel. 14 Additional changes to make it simpler (albeit less accurate) for the rapid

⁸A. W. Mayne, Jr. and J. C. Adams, Jr., "Streamline Swallowing by Laminar Boundary Layers in Hypersonic Flow," AEDC-TR-71-32, Arnold Engineering Development Center, Tullahoma,

⁹A. W. Mayne, Jr. and D. F. Dyer, "Comparisons of Theory and Experiment for Turbulent Boundary La; ers on Simple Shapes at Hypersonic Conditions," *Proc. 1970 Heat Transfer and Fluid Mechanics Institute*, Stanford University Press, 168-188 (1970).

¹⁰S. V. Patankar and D. B. Spalding, "A Finite-Difference Procedure for Solving the Equations of the Two-Dimensional Boundary Layer," Int. J. Heat Mass Transfer 10, 1389-1411 (1967).

¹¹S. M. Price and J. E. Harris, "Computer Program for Solving Compressible Nonsimilar Boundary-Layer Equations for Laminar, Transitional, or Turbulent Flows of a Perfect Gas," NASA TM X-2458 (1972).

¹² J. E. Harris and D. K. Blanchard, "Computer Program for Solving Laminar, Transitional, or Turbulent Compressible Boundary-Layer Equations for Two-Dimensional and Axisymmetric Flow," NASA TM-83207 (Feb 1982).

¹³F. R. DeJarnette and H. H. Hamilton, "Aerodynamic Heating on 3-D Bodies Including the Effects of Entropy Layer Swallowing," J. Spacecr. Rockets 12, 5-12 (Jan 1975).

¹⁴H. J. Fivel, "Numerical Flow Field Program for Aerodynamic Heating Analysis," AFFDL-TR-79-3128, Vol. I, Air Force Flight Dynamics Laboratory, Wright Patterson Air Force Base, Ohio (1979).

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and economical computation of heating rates and surface temperatures throughout an entire trajectory were made by DeJarnette et al. 15

2.2 INVISCID APPROACH

The second simplified approach used to calculate variable BL edge entropy was born of the need to account for entropy layer swallowing over three-dimensional shapes (i.e., space shuttles), where mass balancing techniques become very complicated, and at high-incident angles, where mass balancing using similar BL development overpredicts heat transfer. This approach accounts for entropy layer swallowing by assuming BL edge conditions to be equal to inviscid properties at the hypothetical BL thickness. The BL thickness is found through its relation to the momentum thickness, which is derived from the momentum integral equation using an expression relating Reynolds no. and skin friction. A complete inviscid flow solution is required for this method.

The inviscid technique was originally developed by Zoby, Moss, and Sutton¹⁶ in 1980. BL edge conditions found in this manner, when combined with the approximate heating relations given in Ref. 16, yield favorable heat transfer comparisons over blunted bodies for a variety of wind tunnel and flight conditions, although the technique has been used primarily for high-incidentangle and three-dimensional problems.

2.3 NEW ABBOHT METHOD

The method chosen for incorporation into ABBOHT is a simplified mass balancing version. It retains the advantage of requiring only the inviscid pressure distribution 'as with DeJarnette's method) instead of the entire inviscid flow field (as with the Mayne, Price ... 1 Zoby methods). Moreover, it is simpler than either of the mass balancing methods discussed above because it neither solves the complex BL equations (as with the Mayne and Price methods) nor requires the use of multiple stream functions (as with DeJarnette's method). This new method uses a unique "tangent-blunted-cone" pressure technique (already contained in the old version of ABBOHT) conceived at APL by L. B. Weckesser and developed by L. L. Perini. 17 This approach does not include nonsimilar BL growth, so its ability to do large half-angle cones is limited. For computational efficiency, only simple relations are used for BL growth. models and heating rate correlations.

Presented below is a description of the new method to calculate streamline swallowing effects as incorporated into ABBOHT. The new method also is compared to the old ABBOHT version; experimental data; the prediction methods of Mayne, DeJarnette, and Zoby; and viscous shock layer (VSL) predictions.

3.0 DISCUSSION

The first step in calculating BL edge conditions in ABBOHT is to determine the inviscid surface pressure distribution as described in Ref. 17. To use the mass balancing technique to account for streamline swallow-

ing, the inviscid pressure distribution is coupled with a BL (mass flow rate). To incorporate the required procedure into ABBOHT, two geometrical additions must first be made: laminar and turbulent BL growth models for compressible flow (ABBOHT does not include transition region heating); and the bow shock shape. A dis-

¹⁵F. R. DeJarnette, L. A. Kania, and A. Chitty, "Aerodynamic Heating and Surface Temperatures on Vehicles for Computer-Aided Design Studies," AIAA Paper 83-0411 (Jan 1983).

¹⁶E V. Zoby, J. N. Moss, and K. Sutton, "Approximate Convective Heating Equations for Hypersonic Flows," *J. Spacecr. Rockets* 18, 64-70 (Jan 1981).

¹⁷L. L. Perini and J. B. Kouroupis, "A Simplified Procedure for Calculating Pressure Distributions Over Axisymmetric Blunt Nosed Bodies," JHU/APL BBE/EM-5230 (14 May 1985).

cursion of how the additional ABBOHT constituents are calculated is presented first, followed by an overview of the complete procedure for calculating heat transfer rates and, finally, a comparison of results. The ABBOHT code is written in Fortran 77 and was run on an IBM AT desktop computer for all results.

3.1 BOUNDARY LAYER GROWTH

3.1.1 Laminar Boundary Layer

The governing equation used for mass flow rate in a BL over a conical body is

$$\dot{m} = 2\pi r \rho_e u_e (\delta - \delta^*)$$
.

Therefore, δ and δ^* must be modeled. Since it is desired to know the momentum thickness Reynolds no. as a criterion for BL transition, θ also must be calculated. All BL growth calculations start at the nose/body tangency point. Ness 18 modeled the three BL parameters for compressible, laminar flow over a sharp cone by solving the energy and X-momentum equations assuming Pr = 1, P_e , T_e , M_e , u_e , T_w , ν_w , $\gamma =$ constant and $\beta = 0$. While these are crude assumptions for a blunted cone (especially in the expansion-compression region at the nose/body tangency point), they have been demonstrated herein to be adequate for use in this model. The resulting equations for δ , δ^* , and θ are

$$\delta = \frac{S T_e}{\sqrt{3} \sqrt{u_e S/\nu_w} T_w}$$

$$\left\{ 3.60 \frac{T_w}{T_e} + 2.01 \left[1 + \frac{\gamma - 1}{2} M_e^2 - \frac{T_{\gamma}}{T_e} \right] - 1.62 \frac{\gamma - 1}{2} M_e^2 \right\} ,$$

$$\delta^* = \frac{S T_e}{\sqrt{3} \sqrt{u_e S/\nu_w} T_w}$$

$$\left\{ 0.993 \frac{T_w}{T_e} + 0.383 \frac{\gamma - 1}{2} M_e^2 \right\} ,$$

$$\theta = \frac{0.383 S T_e}{\sqrt{3} \sqrt{u_e S/\nu_w} T_w} .$$

The resulting equation for mass flow rate is

$$m = \frac{2\pi r u_e \rho_e S T_e}{\sqrt{3} \sqrt{u_e S/\nu_w} T_w}$$

$$\left\{ 2.007 \frac{T_w}{T_e} + 2.01 \left[1 + \frac{\gamma - 1}{2} M_e^2 - \frac{T_w}{T_e} \right] - 2.003 \frac{\gamma - 1}{2} M_e^2 \right\}.$$

To account for the initial BL thickness caused by the blunted nose, the stagnation BL thickness is first calculated from Ref. 19 using

$$\delta_s = 6(0.763) \left(\frac{\rho_e \mu_e}{\rho_w \mu_w}\right)^{0.4} \left(\frac{\nu_w}{\beta_s}\right)^{0.5},$$

where

$$\beta_s = \frac{u_{\infty}}{2R_n} \left(1 + \frac{1.56}{\left(1 + M_{\infty}^2\right)^{0.79}} \right) .$$

The equation (obtained from Ref. 20) for the stagnation point velocity gradient is empirical and valid for all free-stream Mach numbers.

The value of δ_s is then added to the sharp cone BL thickness at the nose/body tangency point, yielding the initial BL thickness at the start of the calculations.

3.1.2 Turbulent Boundary Layer

Whereas the laminar BL equations lend themselves to a closed-form solution for BL growth, the turbulent equations do not. Many semi-empirical and correlation methods to predict turbulent BL development are available. The method chosen for use in ABBOHT (the new version) is a flat plate formulation originally proposed for incompressible, turbulent flow by Head 21 in 1958 and then extended for compressible flow by Green 22 in 1967. This method was chosen for its proven accuracy in the flow regime of interest and because it solves directly for the quantity $(\delta - \delta^*)$, which is used for modeling the BL mass flow rate.

¹⁸N'. Ness, "Dynamics of Viscous Fluids," Course Notes, Dept. of Acrospace Engineering, West Virginia University (Sep 1965)

¹⁹R. W. Truitt, Fundamentals of Aerodynamic Heating, The Ronald Press Co., New York (1960).

²⁰L. L. Perini, "Compilation of Experimental Stagnation Point Velocity Gradients and Heat Transfer Data in Subsonic and Supersonic Flow," JHU/APL AEO-75-29 (14 Aug 1975).

²¹M. R. Head, "Entrainment in the Turbulent Boundary Layer," Aeronautical Research Council Reports and Memoranda, R & M No. 3152 (Sep 1958).

²²J. E. Green, "The Prediction of Turbulent Boundary Layer Development in Compressible Flow," J. Fluid Mech. 31, 753-778 (1968).

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The underlying assumption for Head's method is that the BL entrainment rate is proportional to the velocity defect in the outer portion of the BL. The velocity defect can be approximated as the function of a modified form parameter (H_1) multiplied by the external stream velocity, or

entrainment rate
$$=\frac{d(u_e\Delta)}{dx}=u_eF(H_1)$$
,

where

$$H_1 = \frac{\Delta}{\theta}$$

and

$$\Delta = \delta - \delta^*.$$

It was empirically determined that

$$F = 0.0306 (H_1 - 3.0)^{-0.653}$$

for incompressible flow.

Using Head's assertion that density variation in the outer part of the BL had little effect on the entrainment mechanism, Green inferred that the incompressible relationship between F and H_1 also is valid for compressible flow. However, Head's relationship between H (which is used in the momentum integral equation below) and H_1 was inaccurate for compressible flow; therefore, Green provided empirical transformation functions between the compressible and incompressible versions of the form parameters.

Since F is assumed to be unaffected by density variation, Green accounted for compressibility effects simply by inserting density into the entrainment rate equation, yielding

$$\frac{d}{dx} (\rho_e u_e \Delta) = \rho_e u_e F.$$

By expanding the derivative and substituting

$$-\frac{M_e^2}{u_e} \frac{du_e}{dx} \text{ for } \frac{1}{\rho_e} \frac{d\rho_e}{dx} ,$$

Green obtained the following compressible entrainment rate equation:

$$\frac{d\Delta}{dx} = F + (M_e^2 - 1) \frac{\Delta}{u_e} \frac{du_e}{dx} .$$

The momentum integral equation for compressible flow over a flat plate is

$$\frac{d\theta}{dx} = \frac{c_f}{2} - (H + 2 - M_e^2) \frac{\theta}{u_e} \frac{du_e}{dx}.$$

The conventional form parameter, H (for compressible flow), in the above equation is found through an empirical transformation function together with an assumed quadratic BL temperature distribution, which is good for isothermal walls and small pressure gradients. The compressible skin friction (c_f) is dearmined using Eckert's reference temperature transformation between incompressible and compressible flow. Since this growth model was derived for flat plates, the BL growth rate was reduced by a factor of 2.25^{0.2} to compensate for axisymmetric effects. The correction factor for turbulent flow was derived using the Mangler transformation (see Appendix C of Ref. 23). Three-dimensional effects on BL growth are not accounted for, effectively yielding a sharp core BL growth model. As with the laminar BL model, the sharp cone turbulent growth model has been demonstrated herein to be adequate for use in this heat transfer method. It is not the intent of the work reported here to accurately model the structure of the BL, but only to estimate its mass flow rate.

By marching the entrainment and momentum integral equations using an explicit, first-order-accurate technique, the development of the necessary parameters (θ and Δ) for mass flow rate predictions and the momentum thickness Reynolds no. is readily accomplished. Turbulent BL mass flow rate is simply

$$\dot{m} = 2\pi r \rho_e u_e \Delta$$
.

3.2 BOW SHOCK SHAPE

The bow shock shape equation, empirically derived by Billig,²⁴ is used for this model. Billig assumes a hyperbolic shock, asymptotic to the sharp cone-attached shock angle. Since only the bow shock angle is required for streamline swallowing, the equation for coordinates of the shock given by Billig was differentiated to yield the slope as

$$\tan \lambda = \frac{R_c}{v_{ch}} \left(1 + \frac{y_{sh}^2 \tan^2 \eta}{R_c^2} \right)^{0.5}$$

where

$$R_c = 1.143 R_n \exp \left(\frac{0.54}{(M_{\infty} - 1)^{1.2}} \right)$$

and η is the sharp cone-attached shock angle obtained from Simon and Walter²⁵ as

²³C. Gazley, Jr., "Theoretical Evaluation of the Turbulent Skin-Friction and Heat Transfer on Cone in Supersonic Flight," R49A0524, General Electric Co. (Nov 1949).

 ²⁴F. S. Billig, "Shock-Wave Shapes around Spherical- and Cylindrical-Nosed Bodies," *J. Spacecr. Rockets* 4, 822-823 (1967).
 ²⁵W. E. Simon and L. A. Walter, "Approximations for Supersonic Flow Over Cones," *AIAA J.* 1, 1696-1697 (1963).

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$$\sin \eta = \left(\frac{1}{M_{\infty}^2} + \frac{\gamma+1}{2} \sin^2 \sigma\right)^{0.5}.$$

Thus, for a given y_{sh} , R_n , and σ , the slope of the bow shock can be easily found.

4.0 PROCEDURE

4.1 LAMINAR AND TURBULENT FLOW

Streamline swallowing calculations begin at the nose/body tangency point. For laminar BL flow, the procedure progresses as follows:

1. Step surface distance.

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- 2. Calculate new surface pressure (constant downstream of nose region).
- Use current value of BL edge entropy with new pressure to estimate new BL edge properties.
- 4. Calculate new mass flow rate.
- Calculate new radius of free-stream cylinder to match mass flow rate.
- 6. Calculate new bow shock angle at given y_{sh} .
- 7. Calculate new entropy on downstream side of shock.
- 8. Compare entropy from step 7 with previous value.
- 9. If not converged, use entropy from step 7 and repeat procedure beginning with step 3 until converged. All BL edge properties are now thermodynamically consistent and the process repeats again at step 1 until the transition Reynolds no. is reached.

The quantities δ and δ^* are continually calculated for laminar flow and their last two values are saved so that the turbulent equations may be properly initialized. After calculating initial values for a turbulent entrainment and momentum equations, the turbulent streamline swallowing procedure continues as follows:

- 1. Step surface distance.
- 2. Calculate new surface pressure.

- Step entrainment and momentum equations using backward differencing to find new values for Δ and θ.
- 4. Use new values for Δ and θ with BL edge conditions to calculate new form parameter and mass flow rate.
- Calculate new radius of free-stream cylinder to match mass flow rate.
- 6. Calculate new bow shock angle at given y_{sh} .
- Calculate new entropy on downstream side of shock.
- 8. Use new entropy with new surface pressure from step 2 to calculate new BL edge conditions.
- 9. Compare entropy from step 7 with previous value.
- If not converged, use entropy from step 7 and repeat procedure beginning with step 4 until converged.
- Repeat beginning with step 1 until end of body is reached.

There are three parameters driving the streamline swallowing solutions; i.e., the bow shock angle, the body radius, and the surface distance. Consequently, as the bow shock angle approaches that for a sharp cone well downstream of the nose, the BL edge properties also will approach those for a sharp cone. This phenomenon is illustrated in Section 5.0.

4.2 HEAT TRANSFER

Many methods are available to calculate heat transfer rates given BL edge properties and wall temperature. Therefore, to understand better the heat transfer comparisons, a brief review of the heating methods used by ABBOHT is presented below.

4.2.1 Stagnation Point Heating

Stagnation point heating is accomplished with Lees's equation, 26 modified to include wall temperature effects by using Eckert's reference temperature to evaluate density and viscosity. The resulting equation (assuming Pr = 0.72) is

$$q_s = 0.88 ((\rho_* \mu_*)_s \beta_s)^{0.5} (h_r - h_w)_s$$

4.2.2 Laminar Heating

Laminar heating also is accomplished with Lees's method, which requires the stagnation point heating rate as an input. The cold wall heating rate is defined as

$$\dot{q}_w = \frac{q_s \rho. \mu. u_e r}{2 \sqrt{(\rho. \mu.)_s \beta_s S_x}}.$$

4.2.3 Turbulent Heating

The solution of the momentum integral equation with an assumed 1/7-power velocity profile is used for turbulent heating relations. Eckert's reference enthalpy method²⁷ is used to account for compressibility effects and the Reynold's analogy factor of Colburn is used to convert skin friction into a heat transfer coefficient. To convert the flat plate relation into one for an axisymmetric body, a correction factor of 2.25⁰² was used, effectively treating three-dimensional heating effects as constant. The resulting heating rate is

$$\dot{q}_w = \frac{0.0348 \, \rho_* \, u_e}{Re_*^{0.2} \, Pr^{0.67}} \, (h_r - h_w) \ .$$

5.0 COMPARISON OF RESULTS

To illustrate the effects of streamline swallowing on BL edge conditions, results from the old and new versions of ABBOHT will be compared. Figure 2 shows the entropy distribution along the edge of laminar and turbulent BLs up to an S/R_n of 300, with the new model compared to the constant entropy value used in the old model. Also shown for comparison is the sharp cone BL edge entropy. The BL edge entropy with streamline swallowing is seen to decrease rapidly toward the sharp cone asymptote for turbulent BL flow, and more gradually for laminar BL flow. The sharp cone value is 16% below the normal shock value.

Figure 3 compares the edge Mach nos. for the same BL shown in Fig. 2. In this case the edge Mach nos. are heading toward the sharp cone value, rapidly for turbulent flow and gradually for laminar flow. The increase in edge velocity from the classical solution will have a direct effect on heat transfer rates as shown by the heating equations in Section 4.2. Although the effect of increased velocity significantly increases the heat transfer coefficient, the increased heating rate is moderated by an accompanying decrease in the recovery enthalpy.

ABBOHT can be run using either ideal or equilibrium air properties. Except when noted otherwise, all cases presented herein were run with the latter.

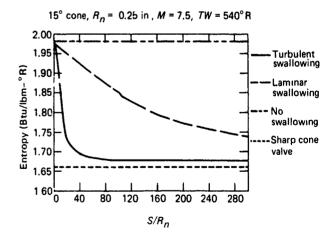


Figure 2 Entropy along a boundary layer edge.

²⁶L. Lees, "Laminar Heat Transfer Over B. ant-Nosed Bodies at Hypersonic Flight Speeds," *Jet Propul.* 26, 259-269 (1956).

²⁷E. R. G. Eckert, "Engineering Relations for Friction and Heat Transfer to Surfaces in High Velocity Flow," J. Aeronaut. Sci. 12, 585-587 (1955).

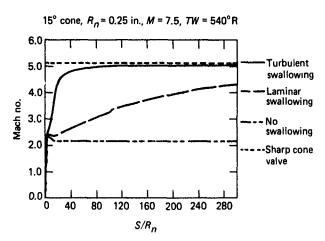


Figure 3 Mach no. along a boundary layer edge.

The laminar heating distributions for the old and new versions of ABBOHT are compared to experimental data from Ref. 28 in Fig. 4. Included with the test conditions is Lees's stagnation point heating rate (none of the experimental data presented included a measurement of stagnation point heating). Both codes accurately predict laminar heating rates for the given conditions. Streamline swallowing has very little effect on heating rates in the nose region of this body.

Figure 5 shows the laminar heating distribution for a less severe heating condition.²⁹ Here again, the two theories fit the data equally well. Laminar heating predictions are within 10% of the experimental data in Figs. 4 and 5.

The locations most affected by streamline swallowing are downstream of the nose region in the turbulent BL flow regime. This point is best illustrated in Fig. 6, which shows heat transfer to a slightly blunted 5° cone at Mach 10. The difference between the old and new versions of ABBOHT is approximately 20% in the turbulent flow regime. Results from both versions are compared to Mayne's method as well as experimental data obtained by Mayne. The turbulent heating distribution predicted by ABBOHT is not as high as

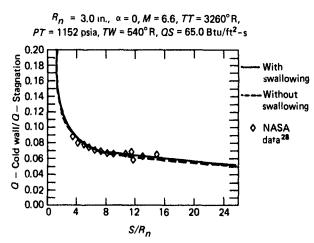


Figure 4 Heat transfer on a 12.5° blunted cone.

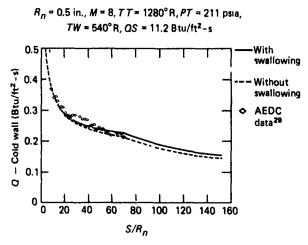


Figure 5 Heat transfer on a 7° blunted cone.

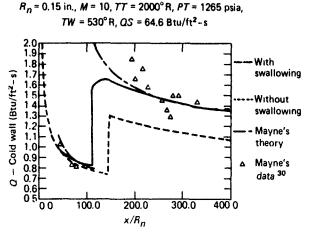


Figure 6 Heat transfer on a 5° blunted cone.

²⁸ R. J. Nowak, C. W. Albertson, and L. R. Hunt, "Aerothermal Tests of a 12.5° Con at Mach 6.7 for "Yarious Reynolds Numbers, Angles of Attack, and Nose Shap...," NASA TP-2345 (Jan 1985).

²⁹D. B. Carver, "Heat Transfer, Surface Pressure and Flow-Field Surveys on Conic and Biconic Models with Boundary Layer Trips at Mach Number 8—Phases IV and VI," AEDC-TSR-80-V14, Arnold Engineering Development Center, Tullahoma, Tenn. (Mar 1980).

³⁰ A. W. Mayne, Jr., "Calculation of the Boundary-Layer Flothe Windward Symmetry Plane of a Spherically Blunted Axisymmetric Body at Angle of Attack, Including Streamline-Swallowing Effects," AEDC-TR-73-166, Arnold Engineering Development Center, Tullahoma, Tenn. (Oct 1973).

Mayne's theory at $x/R_n < 250$ but converges with it at the sharp cone value farther downstream. The turbulent experimental data have considerable scatter and range from 19% higher to 10% lower than the new AB-BOHT predictions. This is a marked improvement from the solution without swallowing, which ranges from 13 to 48% lower than the experimental data in the turbulent flow regime. Laminar flow calculations show a slightly better correlation to experimental data for AB-BOHT results rather than for Mayne's theory.

Figures 7 and 8 show additional comparisons to perimental turbulent data. In general, the curves with swallowing overpredict heat transfer in the fully turbulent flow regime by 5 to 15%, while those without swallowing underpredict heating from 10 to 25%. In Fig. 8, a BL trip was used at an S/R_n of 4. It is believed that low Reynolds no. turbulent flow (low BL vorticity) induced significant vorticity interaction in the

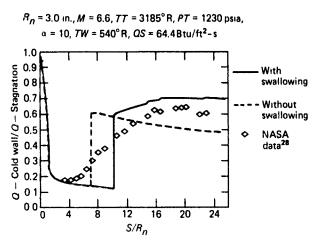


Figure 7 Heat transfer on a 12.5° blunted cone.

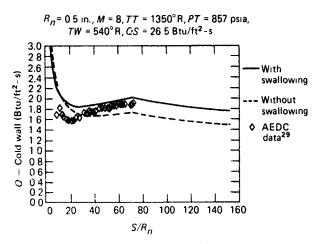


Figure 8 Heat transfer on a 7° blunted cone.

nose region of this body, accounting for the high estimate of heat transfer at $S/R_n < 30$. In addition to improving heating rate predictions by 5 to 10%, the method with swallowing also produces heating rate distributions more representative of the trends in the data.

To assess ABBOHT's performance with streamline swallowing at a higher Mach no., two cases were run with ideal air properties for comparison with the results of the DeJarnette and Zoby methods, obtained from Ref. 31. Additionally, a VSL solution, which accurately models variable entropy as well as vorticity interaction effects (also obtained from Ref. 31), is given. Figures 9 and 10 show turbulent heating results for a 5° cone at Mach 15 and angles of attack of 0 and 20°, respec-

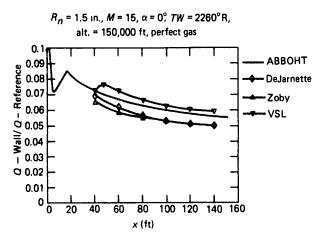


Figure 9 Turbulent heating on a 5° cone.

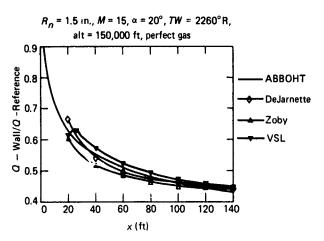


Figure 10 Turbulent heating on a 5° cone.

³¹E. V. Thompson, E. V. Zoby, K. E. Wurster, and P. A. Gnoffo, "An Aerothermodynamic Study of Slender Conical Vehicles," AIAA Paper No. 87-1475, presented at AIAA 22nd Thermophysics Conf. (Jun 8-10, 1987).

tively. In both cases, ABBOHT is generally higher than the DeJarnette and Zoby solutions and below the VSL solution. The total spread in all four solutions is approximately 18%. Usually, a VSL solution is considered the most accurate since it most closely models the physics of fluid heat and momentum transfer. However, without experimental data, it is impossible to support this presumption. Nevertheless, the close proximity of the ABBOHT solution to the VSL solution is a positive result. It also is encouraging that ABBOHT accurately modeled turbulent heat transfer on a blunted cone with a moderately high flow incidence angle (25°) at high Mach no. and altitude conditions, where vorticity interaction is moderate.

To appreciate the limits of the new ABBOHT version, a case was run that included high vorticity interaction. The body was a 40° sphere cone with a 1-ft nose radius. The flow conditions were obtained from Ref. 32. For turbulent flow, transition was assumed to be instantaneous at the nose/body tangency point. The resulting laminar and turbulent heating distributions are compared to Mayne's method and a VSL solution from Ref. 32 in Fig. 11.

Both ABBOHT and Mayne's turbulent streamline swallowing technique (neither of which account for vorticity interaction) overpredict the turbulent VSL solution by as much as 60 and 40%, respectively. A check of the pressure distribution and entropy swallowing distance in ABBOHT revealed them to be approximately the same as the VSL solution. Sources of error in the ABBOHT solution include the absence of a well-defined BL edge caused by vorticity interaction and loss of ac-

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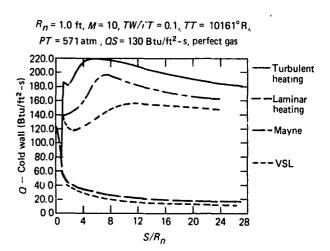


Figure 11 Heat transfer on a 40° blunted cone.

curacy in the turbulent heating relation at high incidence angles. Because of the limited range of the approximations employed, ABBOHT should be used only to predict turbulent heating to axisymmetric bodies with incidence angles of less than 25°.

Laminar heating predictions were within 3% of the VSL solution for Mayne's method (not shown) and within 10% for ABBOHT. The favorable comparison for laminar flow suggests that ABBOHT can be used at 'high incidence angles to predict laminar heating under these conditions. The equivalent cone method (summing the cone angle and angle of attack) does not work well for laminar flow³³ and should therefore be avoided.

6.0 SUMMARY AND CONCLUSIONS

A simplified technique has been developed to add streamline swallowing to an inviscid axisymmetric heat transfer code named ABBOHT. Streamline swallowing effects are significant downstream of the nose region on axisymmetric blunt bodies where BL edge entropy

is significantly lower than in the nose region. To account for variable BL entropy, a mass balancing technique was used to couple the inviscid pressure distribution with mass flow rates from newly added BL devel-

³²E. C. Anderson and D. C. Wilcox, "Vorticity Interaction Effects on Blunt Bodies," NASA CR-2778 (Jan 1977).

¹³E. V. Zoby and A. L. Simmonds, "Engineering Flowfield Method with Angle-of-Attack Applications," J. Spacecr. Rockets 22, 398 (1985).

opment models. In addition to the BL growth models, only an empirical bow shock definition was required to complete the geometry for the new procedure. The new ABBOHT code is simpler than previous mass balancing techniques because it does not solve the complete BL equations, it does not include the use of stream functions, and it does not require a definition of the entire inviscid flow field.

Compressible laminar BL growth was calculated directly with Ness's equations ¹⁸ for the BL and displacement thicknesses (see subsection 3.1.1). Compressible turbulent BL development was accomplished using Green's method, ²² which marches the first-order BL momentum integral equation together with the mass entrainment equation. Both procedures require iteration for BL edge conditions.

Comparisons to the old version of ABBOHT indicate a significant increase in turbulent heat transfer (from 10 to 30%) aft of the nose region. New ABBOHT heating results matched experimental data almost as well as Mayne's method for a 5° blunted cone in Mach 10

flow. In general, experimental data ranged from 19% higher to 10% lower than ABBOHT predictions; virtually all of the scatter was associated with turbulent flow cases. Turbulent heating comparisons to DeJarnette, Zoby, and VSL solutions at Mach 15 were very good up to a flow incidence angle of 25°. However, at a larger incidence angle (with high vorticity interaction), ABBOHT significantly overpredicted heat transfer rates. Laminar heating was only slightly higher with streamline swallowing and within 10% of the experimental results.

Until further validation runs and improvements to the code are made, the Mach 15 case with an incidence angle of 25° should be considered the upper bound of the applicability range for the new ABBOHT code. Above 25°, turbulent heat transfer calculations will be high. A listing of the ABBOHT source code with all subroutines (except the air property curve fitting algorithm) is contained in Appendix A and the variable definitions are presented in Appendix B.

ACKNOWLEDGMENTS

The author gratefully acknowledges F. T. Buckley and L. L. Perini for their help and guidance throughout the development stages of the ABBOHT code. This work was conducted under the supervision of L. B. Weckesser, Supervisor of the Bumblebee Engineering Group at APL.

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²⁹D. B. Carver, "Heat Transfer, Surface Pressure and Flow-Field Surveys on Conic and Biconic Models with Boundary Layer Trips at Mach Number 8—Phases IV and VI," AEDC-TSR-80-V14, Arnold Engineering Development Center, Tullahoma, Tenn. (Mar 1980).

³⁰A. W. Mayne, Jr., "Calculation of the Boundary-Layer Flow in the Windward Symmetry Plane of a Spherically Blunted Axisymmetric Body at Angle of Attack, Including Streamline-Swallowing Effects," AEDC-TR-73-166, Arnold Engineering Development Center, Tullahoma, Tenn. (Oct 1973). ³¹E. V. Thompson, E. V. Zoby, K. E. Wurster, and P. A. Gnoffo, "An Aerothermodynamic Study of Slender Conical Vehicles," AIAA Paper No. 87-1475, presented at AIAA 22nd Thermophysics Conf. (Jun 8-10, 1987).

³²E. C. Anderson and D. C. Wilcox, "Vorticity Interaction Effects on Blunt Bodies," NASA CR-2778

(Jan 1977).

³³E. V. Zoby and A. L. Simmonds, "Engineering Flowfield Method with Angle-of-Attack Applications," J. Spacecr. Rockets 22, 398 (1985).

6

APPENDIX A

PROGRAM TO COMPUTE HEAT TRANSFER ON BLUNT BODIES VERSION 2.0, JULY 1987 ENTHALPY BASE OF OUTPUT IS O'R, ENTHALPY BASE OF AIRTBL USED IN CODE IS O'R

С MAIN PROGRAM COMMON NOUT, NP, XTAB(100), YTAB(100), DSO, TO, PO, PTO, TTO, ALF, TIME, 1 HRT(50), RUC(50), STA(50), XLEN(50), NPTS, ZO, VO, STRAN, RN, DELC, 2 RR.RG.LT.ISTEP.IX.SDIST(10), FREEM(20,10), EDGEMR(20,10), 3 EDGEPR(20,10), NFIL, NUM, JSTEP, ITY, IAIR COMMON/ALPHAN/TITLE, HEAT, CONV, BUG, TYPE, QS, TRAN, TURB, GEO, LAM COMMON/LOGICAL/NURL CHARACTER*1 QS, NURL CHARACTER*3 CONV, BUG, HEAT, LAM CHARACTER*4 TYPE, TRAN, TURB, GEO CHARACTER*7 NFORMAT(10) CHARACTER*60 TITLE CHARACTER*80 FILE5, FILE6, FILE7, FILE8, FILE9, FILE10, FILE11, FILE12, 1FILE13, FILE14, FILE15, FILE16, FILE17, FILE18 REAL*4 MACH.MO.LT DATA NFORMAT/'FIRST', 'SECOND', 'THIRD', 'FOURTH', 'FIFTH', 'SIXTH', 1'SEVENTH', 'EIGHTH', 'NINTH', 'TENTH'/ C ----- NAME INPUT AND OUTPUT FILES -----924 FORMAT(A80) 925 FORMAT(30H INPUT DATA FILE -? ١ WRITE(0,925) READ(0,924)FILE5 OPEN(5, FILE-FILE5) 926 FORMAT(30H OUTPUT DATA FILE =?) WRITE(0,926) READ(0,924)FILE6 OPEN(6, FILE-FILE6) 928 FORMAT(30H PLOT OUTPUT FILE =? WRITE(0,928) READ(0,924)FILE8 OPEN(8, FILE-FILE8) IX--1 C READ INPUT READ(5,910,ERR-998) TITLE READ(5,914) IAIR, ITY, IQS, ITR, IGE, NPTS, NOUT, NP READ(5,915) DELC,RN,RR,RG,ALF,LT,DSO,STRAN IF(ITY.EQ.1)TYPE='FLT IF(ITY.EQ.2.OR.ITY.EQ 3)TYPE-'TEST' IF(IQS.EQ.1)QS='L' IF(IQS.EQ.2)QS='D' IF(ITR.EQ.1)TRAN='REYS' IF(ITR.EQ.2)TRAN='REYT' IF(ITR.EQ.3)TRAN='PANT' IF(IGE.EQ.1)GEO-'CONE' IF(IGE.EQ.3)GEO-'FLAT' IF(IGE.EQ.4)GEO-'DISK' IF(IGE EQ 5)GEO-'SPHE' IF(IGE EQ.6)GEO-'CYLI'

```
C ----- READ NUMBER OF URLIM FLOW TABLES TO CREATE -----
     WRITE(0,1003)
1003 FORMAT(1X, 'CREATE URLIM LOCAL FLOW TABLES? (Y/N)' )
     READ(0,1004)NURL
 1004 FORMAT(A1)
     IF(NURL.EQ.'Y'.OR.NURL.EQ.'y')THEN
     WRITE(0,929)
C ----- READ FLOW DISTANCE TO EACH STATION (FT) -----
  929 FORMAT(1X,45H NUMBER OF FLOW STATIONS (UP TO 10) - ?
     READ(0,930)NUM
  930 FORMAT(15)
     WRITE(0,960)
  960 FORMAT(5X, LIST SURFACE DISTANCE TO EACH STATION (FT) USING FREE
     READ(0, *)(SDIST(1), I=1, NUM)
     NEWNUM-8 + NUM
     DO 12 I-9, NEWNUM
     WRITE(0,939)NFORMAT(1-8)
  939 FORMAT(1X,' FILE NAME FOR ',A7,' STATION - ?')
      IF(I.EQ.9)THEN
     READ(0,924)FILE9
     OPEN(I, FILE-FILE9)
      ELSEIF(I.EQ.10)THEN
      READ(0,924)FILE10
      OPEN(I, FILE-FILE10)
      ELSEIF(I.EQ.11)THEN
      READ(0,924)FILE11
      OPEN(I, FILE-FILE11)
      ELSEIF(I.EQ.12)THEN
      READ(0,924)FILE12
      OPEN(I, FILE-FILE12)
      ELSEIF(I.EQ.13)THEN
      READ(0,924)FILE13
      OPEN(I, FILE-FILE13)
      ELSEIF(I.EQ.14)THEN
      READ(0,924)FILE14
      OPEN(I, FILE-FILE14)
      ELSEIF(I.EQ.15)THEN
      READ(0,924)FILE15
      OPEN(I, FILE-FILE15)
      ELSEIF(I.EQ.16)THEN
      READ(0,924)FILE16
      OPEN(I, FILE-FILE16)
      ELSEIF(I.EQ.17)THEN
      READ(0,924)FILE17
      OPEN(I, FILE-FILE17)
      ELSEIF(I.EQ.18)THEN
      READ(0,924)FILE18
      OPEN(I, FILE-FILE18)
      ENDIF
   12 CONTINUE
      ENDIF
C ..... READ WALL TEMPS AT NPTS STATIONS .....
      IF (NPTS.EQ 0) GO TO 1000
      READ(5,915) (XLEN(I), I=1, NPTS)
      READ(5,915) (STA(I), I=1, NPTS)
```

```
C ----- READ INPUT FLOW PARAMETERS -----
     IF(ITY.EO.1.OR.ITY.EO.2) GO TO 549
     READ(5,915,END-999)TIME,ZO,VO,PTO,TTO
     GO TO 551
 549 READ(5,915,END-999)TIME,ZO,VO,PO,TO
 551 JSTEP-JSTEP+1
 910 FORMAT(A60)
 914 FORMAT(1015)
 915 FORMAT(7F10.0)
C ----- CALL AEROTHERMAL HEATING (AND PRESSURE DIST) SUBROUTINE
     CALL ODIST
     GO TO 1000
C ----- CONSTRUCT URLIM TABLES IN SEPARATE FILES ------
  999 IF(NURL.EQ.'Y'.OR.NURL.EQ.'y')THEN
     NFIL-9
     DO 11 J-1, NUM
     WRITE(NFIL, 901)SDIST(J)
     WRITE(NFIL, 902)
C ------ WRITE VALUES IN URLIM TABLES FOR M=0.1 ----
     WRITE(NFIL, 903)0.,1.,1.
     WRITE(NFIL, 903)1.,1.,1.
  901 FORMAT(1X, 'LOCAL FLOW TABLE FOR STATION AT S=',F10.2,1X,'FT')
  902 FORMAT(10X,'M0',13X,'M/M0',11X,'P/P0')
C ----- WRITE URLIM FLOW TABLES FOR M > 1 -----
     WRITE(NFIL,903)(FREEM(I,J),EDGEMR(I,J),EDGEPR(I,J),I-1,JSTEP)
  903 FORMAT(1X,F12.4,2F14.4)
     NFIL-NFIL+1
  11 CONTINUE
     ENDIF
     IF(IX.EQ.1) GO TO 900
     IF(IX.EQ.1) GO TO 998
     IX-IX-1
     END
C ----- C-- END MAIN PROGRAM -----
C ----- AEROTHERMAL HEATING (AND PRESS. DIST.) SUBROUTINE ----
     SUBROUTINE QDIST
C /*-----
C
     THIS SUBROUTINE (QDIST) USES,
С
      ATM THE 1962 STANDARD ATMOSPHERE
C
      AIRTBL MAIN DRIVER FOR AIR PROPERTIES
      WRKHAT THE CURVE-FIT AIR PROPERTIES
      PIF1 LINEAR INTERPOLATION
     COMMON NOUT, NP, XTAB(100), YTAB(100), DSO, TO, PO, PTO, TTO, ALF, TIME,
    1 HRT(50), RUC(50), STA(50), XLEN(50), NPTS, ZO, VO, STRAN, RN, DELC,
    2 RR, RG, LT, ISTEP, IX, SDIST(10), FREEM(20,10), EDGEMR(20,10),
    3 EDGEPR(20,10), NFIL, NUM, JSTEP, ITY, IAIR
     COMMON/ALPHAN/TITLE, HEAT, CONV, BUG, TYPE, QS, TRAN, TURB, GEO, LAM
     COMMON/LOGICAL/NURL
     CHARACTER*1 QS, NURL
```

LAUREL, MARYLAND

REAL*4 NUW, NUE, HDOT, HE2, HO2, MNORM, JUNK, JUNK1, JUNK2, JUNK4 DIMENSION STAB(100)

```
C ----- INIATIALIZE VARIABLES AND CONSTANTS -----
      HREF-8465.0
     PREF-2116.224
     TGJ-50062.744
     TDUM-1.
     GAM-1.40
     CPO-0.24
     RAD-57.2957795
     DTR-1.0/RAD
     SO-1.0E-5
     RH00-1.0
     A0-1.0
     WO-1.0
     PW-1.0
     TST-1.0
     HS-1.0
     SST-1.0
     RHOST-1.0
     AST-1.0
     WST-1.0
     MMARKER-0
     MARKER-0
     IFLAG-0
     DBL1-0.
     DBL2-0.
     DDD-0.
     DD1-0.
     DD2-0.
     VE1-0.
     VE2-0.
     TTS-1.0
     TE-1.0
     HW-1.0
     PR-0.72
     IFLAG1-0
     RHOS-1.0
     HE-1.0
     SW-1.0
     SS-1.0
     RHOE-1.0
     RHOW-1.0
     MUREF-1.15312E-5
     RHREF-0.0803707
     DIM-1.0
     11-1
     12-2
     I4-4
     15-5
     PI=3.14159
     KK-0
     CONV - 'YES'
     LAM-'YES'
     SMAX - 1.1*XLEN(NPTS)
     NN-0
     1X - 1
     DIM - 1.0
     RET-0.0
     DS - DSO
```

```
FSXL-0.0
     SX-0.0
     FSTL-0.0
     ST-0.0
     RES-0.0
     SR-0.0
     SL-0.0
     KKK-0
     IF (TYPE.NE.'TEST') GO TO 260
C ..... INPUT TOTAL FREE STREAM TEST CONDITIONS .....
     SSO-0.
     IF(ITY.EQ.2)GO TO 261
     IF(IAIR.EQ.1)THEN
     CALL PAIR(PTO, TTO, HTO, SSO, DU1, DU2, 14)
     CALL AIRTBL(PTO/144.,TTO,HTO,SSO,DU1,DU2,DU3,I4,N)
     ENDIF
     HO = HTO - VO**2/TGJ
     IF(IAIR.EQ.1)THEN
     CALL PAIR (PO, TO, HO, SSO, RHOO, AO, 15)
     PO-PO/144.
     CALL AIRTBL(PO, TO, HO, SSO, RHOO, AO, DU3, I5, N)
     ENDIF
     A0-49.014*SQRT(TO)
     MO-VO/AO
     PO-PO*144.
     GO TO 262
C-----INPUT STATIC FREE STREAM TEST CONDITIONS-----
  261 AO-49.014*SQRT(TO)
     GO TO 280
C-- - --- INPUT FLIGHT CONDITIONS------
  260 CALL ATM(ZO, PO, TO, DU1, AO, RHOO)
  280 MO-VO/AO
C ----- CALCULATE TOTAL ENTHALPY -----
     HTO = VO**2/TGJ + CPO*TO
C --- CALCULATE OTHER FREE STREAM STATIC AND TOTAL CONDITIONS-----
     SSO=0.
      IF(IAIR.EQ.1)THEN
      CALL PAIR(PO,TO,HO,SSO,RHOO,AO,I4)
      CALL PAIR(PTO, TTO, HTO, SSO, DU1, DU2, I5)
      ELSE
      CALL AIRTBL(PO/144.0,TO, HO, SSO,RHOO,AO,WO,I4,N)
      CALL AIRTBL(PTO, TTO, HTO, SSO, DU1, DU2, DU3, 15, N)
      PTO-PTO*144.0
      ENDIF
C ----- CONDITIONS BEHIND SHOCK -----
  262 IF(IAIR.EQ.1)THEN
     CALL PGNS (MO, SSO, SS2, R2R1)
      ELSE
```

```
IF(IAIR.EQ.1)THEN
     CALL PAIR(PTS, TTS, HTO, SS2, RHOS, AS, 15)
     ELSE
     CALL AIRTBL(PTS,TTS,HTO,SS2,RHOS,AS,WS,15,N)
     PTS - PTS*144.0
     ENDIF
     MO2 - MO*MO
C ----- STAG, PT. VELOCITY GRADIENT FOR SPHERE -----
       BETA = (VO/2,/RN)*(1.+1.56/(1.+MO2)**.79)
C ----- COHEN CORRELATIONS AT STAG. PT.-----
       RHOMUE = (0.225*(PTS/PREF)**0.992)/
                (1.0-1.0213*(1.0-(HTO/HREF)**0.3329))
       TW-TTS
       SSW-0.
       IF(IAIR.EQ.1)THEN
       CALL PAIR (PTS, TW HW, S5W, RHOW, AW, 14)
       ELSE
       CALL AIRTBL(PTS/144., TW, HW, SSW, RHOW, AW, WW, 14, N)
       ENDIF
       RHOMUW = (0.225*(PTS/PREF)**0.992)/
                (1.0-1.0213*(1.0-(HW/HREF)**0.3329))
       RHOMUE-RHOMUE*MUREF*RHREF
       RHOMUW-RHOMUW*MUREF*RHPEF
       NUE-RHONUE/RHOS**2.
       NUW-RHOMUW/RHOW**2.
C ------ STAG. PT. BOUNDARY LAYER THICKNESS -----
     DDELTAS = 6.* 0.763* (RHOMUE/RHOMUW)**0.4
               *(NUW/BETA)**0.5
C ----- VON KARMAN GEOMETRY (WITH 35 DEG NOSE TIP)----
     IF(GEO.NE.'VK') GO TO 14
     DEL-DELC+ALF
     XT = RN*(1.0-SIN(DEL*DTR))
     XTC- RN*(1.0-SIN(DELC*DTR))
     YT - RN*(COS(DEL*DTR))
     YTC- RN*(COS(DELC*DTR))
     STN - RN*(90.0-DEL)/RAD
     SRTP-YT
     CALL SCONE(GAM, PC, MO, DEL, PO)
C -----*/
  14 IF (GEO.NE.'BLOG') GO TO 300
     DELTA-ACOS((RG-RR)/(RG-RN))
     DELTA-DELTA*RAD
     DEL-DELTA + ALF
     RRR=(RN-RG)*COS(DEL*DTR) + RG
     YT=RG*(RG-RRR)/(RG-RN)+RRR-RG
     YTC=RG*(RG-RR)/(RG-RN)+RR-RG
     XT=RN-SQRT(RN**2,-YT**2,)
     STN = 2.0*RN*ASIN(SQRT(%1**2.+YT**2.)/2./RN)
     TH1 = 90.0 - (180.0 + STN/RN/PI)
 300 IF(GEO.NE.'CONE') GO TO 320
```

```
C ----- BLUNTED CONE GEONETRY -----
     XT -RN*(1.0 - SIN(DEL*DTR))
     YT - RN * COS(DEL*DTR)
     YTC - RN * COS(DELC*DTR)
     XTC-RN*(1.0-SIN(DELC*DTR))
     STN-RN*(90.0-DEL)/RAD
     SRTP-YT
C----- STAGNATION POINT VELOCITY GRADIENTS FROM PERINI ------
 320 SS-SS2
     IF(GEO.EQ.'SPHE'.OR.GEO.EQ.'CONE'.OR.GEO.EQ.'ENNK'.OR.
    1 GEO.EQ.'BLOG'.OR.GEO.EQ.'VK')
    2DUEDS=(VO/2./RN)*(1.1+1.56/(1.+MO2)**.79)
C ----- CHECK FOR CONVERGENCE IN AIRTBL -----
     IF(N.LE.1) GO TO 330
     WRITE(6,920)
 920 FORMAT(22H NO CONV, GO TO NEXT
     CONV - 'NAY'
     RETURN
C ----- BEGIN MARCHING -----
 330 S- SO-DS
 100 SL - S
     S = S + DS
     IF(GEO.EQ.'VK'.AND.S.GE.(STN+0.04134))GO TO 1505
 1504 SEFF-SEFF + DS
     XF-0.0
     GO TO 1502
C ----- GEOMETRY FOR VON KARMAN -----
 1505 PHI1=ACOS(1.-(2.*X/LT))
     Y1=RR*SQRT((PHI1-(SIN(2.*PHI1))/2.)/PI)
     PHI2=ACOS(1.-(2.*(X+DX)/LT))
     Y2=RR*SQRT((PHI2-(SIN(2.*PHI2))/2.)/PI)
     DY-Y2-Y1
C----- COORDINATE TRANSFORMATION FOR VK ANGLE OF ATTACK -----
     XXX1=X-Y1*TAN(ALF*DTR)
     XXX2=(X+DX)-Y2*TAN(ALF*DTR)
     YYY1-(Y1/COS(ALF*DTR)) + XXX1*TAN(ALF*DTR)
     YYY2=(Y2/COS(ALF*DTR)) + XXX2*TAN(ALF*DTR)
     DYYY=YYY2-YYY1
     DXXX-XXX2-XXX1
C ----- INCIDENCE ANGLE FOR VK AT ANGLE OF ATTACK -----
     THL-TH
     TH-ATAN(DYYY/DXXX)*RAD
     S=S-DS
     DS-SQRT(DX**2+DY**2)
     RADIUS=Y1+DY
     S=S+DS
     X=X+DX
     Y-Y1+DY
```

```
1502 IF(TST.GT.1080..AND.IAIR.NE.1) GAM-1.4493-4.535E-5*TST
     IF(TST.GT.3600..AND.IARI.NE.1) GAM-1.29
C ----- CALCULATE LOCAL REYNOLDS NUMBERS -----
     IF(KKK.EQ.0)GO TO 416
     RHOMUE = (0.225 * (PE/PREF)**0.992)/
               (1.C - 1.0213 * (1.0-(HE/HREF)**0.3329))
     RHOMUE-RHOMUE*MUREF*RHREF
     NUE-RHOMUE/RHOE**2.
     IF(KKK.EQ.0)NUE-NUW
 416 RES-VE*S/NUE
     RET-VE*DM/NUE
     IF(TRAN.EQ.'REYS'.AND.RES.LT.STRAN)GO TO 15
     IF(TRAN.EQ, 'REYT'.AND.RET.LT.STRAN)GO TO 15
     IF(MARKER.LE.2.OR.S.LE.STN.OR.KKK.EQ.0)LAM-'YES'
     GO TO 19
  15 LAM-'YES'
C -----*/
C ----- SPHERICAL PORTION OF VK NOSE -----
  19 IF(GEO.NE.'VK')GO TO 16
     IF(S.GE.STN)GO TO 341
     TH-(S/RN) *RAD
     X = RN*(1.-COS(TH*DTR))
     PE-PTS-(PTS-PO)*(SIN(TH*DTR)**2)
     Y = RN*SIN(TH*DTR)
     SR-Y
     TH-90.-TH
     GO TO 101
C ----- CONE PORTION OF VK NOSE -----
  341 IF(S.GE.(STN+.04134))GO TO 342
     X = XT + (S-STN)*COS(DEL*DTR)
     Y = YT + (S-STN) * SIN(DEL*DTR)
     SR - Y
     RADIUS - YTC + (S-STN)*SIN(DELC*DIR)
     TH - DEL
     CALL BCONE(PE, PC, DEL, RN, X, S, MO)
     GO TO 101
C ----- VK PORTION OF VK CONTOUR -----
 342 IF(TH.GF.O.3) GO TO 20
     WRITE(6,1501)
1501 FORMAT( ' BODY SLOPE < 0.3 DEG - STOP CALCULATIONS')
     RETURN
  16 IF(GEO.NE.'CONE') GO TO 400
C ---BLUNTED CONE PRESSURES, (BLICK & FRANCIS, AIAA JR., V.4,#3) */
     IF(S.GT.STN) GO TO 340
     TH -(S/RN)*RAD
     X = RN*(1.0-COS(TH*DTR))
PE = PTS -(PTS-PO)*(SIN(TH*DTR)**2)
     Y = RN*SIN(TH*DTR)
     SR-Y
```

```
RADIUS-YTC+(X-XTC)*TAN(DELC*DTR)
     SR-Y
     TH-DEL
     CALL BCONE(PE, PC, DEL, RN, X, S, MO)
     GO TO 101
C -----END OF CONE -----
C-----BLOG SPHERICAL NOSE-----
 400 IF(KK.EQ.1) GO TO 1013
     IF(S.GT.STN) GO TO 410
     TH-90.0-(180.0*S/RN/PI)
     X-RN*(1.0-SIN(TH*DTR))
     "-RN*COS (TH*DTR)
     JR-Y
     PE-PTS-(PTS-PO)*SIN((90.0-TH)*DTR)**2
     CALL XMACH (GAM, ME, PE/PTS)
     THL - TH
     GO TO 101
C ---- NEED CONDITIONS EXACTLY AT TANGENCY POINT, SO IF WE ALREADY
C ---- STEPPED PAST IT WE RETURN TO TANG PT EXACTLY -----
  410 KK-1
     TH-90.0-(180.0*STN/RN/PI)
     X=RN*(1.0-Sin(TH*DTR))
     Y-RN*COS (TH*DTR)
     RADIUS-RN*COS(TH*DTR)
     PE=PTS-(PTS-PO)*SIN((90.0-TH)*DTR)**2
     CALL XMACH(GAM, ME, PE/PTS)
     THL - TH
     GO TO 101
C-----OGIVE SURFACE-----
 1013 DELT-DS*180.0/PI/RG
     TH - THL-DELT
     IF(TH.GE.O.3) GO TO 420
     WRITE(6,919)
  919 FORMAT( ' BODY SLOPE < 0.3 DEG STOP CALCULATIONS')
     RETURN
  420 X = XT+2.0*RG*SIN((TH1-TH)*DTR/2.0)*COS((TH1+TH)*DTR/2.0)
     Y=YT+2.0*RG*SIN((TH1-TH)*DTR/2.0)*SIN((TH1+TH)*DTR/2.0)
     SR-Y
     THC-TH-ALF
     TH1C-TH1-ALF
     RADIUS=YTC+2.0*RG*SIN((TH1C-THC)*DTR/2.0)*SIN((TH1C+THC)*DTR/2.0)
  20 IF(TH.LE.3.0) GO TO 430
C ----- SHARP CONE PRESSURE -----
     CALL SCONE (GAM, PC, MO, TH, PO)
     XF=RN*(1.0-SIN(TH*DTR))+(Y-RN*COS(TH*DTR))/TAN(TH*DTR)
     IF(GEO, EQ. 'VK')
    1XF-RN*(1.0-SIN(TH*DTR))+(YYY2-RN*COS(TH*DTR))/TAN(TH*DTR)
C ----- BLUNTED CONE PRESSURE FROM SHARP CONE PRESSURE -----
     CALL BCONE(PE, PC, TH, RN, XF, S, MO)
 430 CALL PRMY(GAM, PE, DELT, ME, PE)
  440 CALL XMACH(GAM, ME, PE/PTS)
```

```
101 N-1
C ----- WALL CONDITIONS -----
     CALL PIF1(TW,S,XLEN,NPTS,STA)
     PW - PE
     SSW-0.
     IF(IAIR, EQ. 1) THEN
     CALL PAIR (PW, TW, HW, SW, RHOW, AW, 14)
     ELSE
     CALL AIRTBL(PW/144.0, TW, HW, SSW, RHOW, AW, WW, I4 , N)
     ENDIF
C ----- CHECK FOR TURBULENCE -----
     IF(LAM, EQ. 'NO')GO TO 63
  B.L. EDGE CONDITIONS -----
  60 IF(KKK.EQ.0) PE-PTS
     IF(IAIR.EQ.1)THEN
     CALL PAIR (PE, TE, HE, SS, RHOE, AE, I1)
     ELSE
     CALL AIRTBL(PE/144.0, TE, HE, SS, RHOE, AE, WE, I1, N)
     ENDIF
     IF(KKK.EQ.0) HE-HTO
     VE-MAX(1.0,TGJ*(HTO-HE))
     VE-SQRT(VE)
     AE-49.014*SQRT(TE)
     ME-VE/AE
     IF(IFLAG.GE.1) GO TO 56
     ME2 - ME * ME
     IF(S.LT.STN) GO TO 99
     IF(MARKER.GE.1) GO TO 51
C -- CALCULATE EFFECTIVE SHARP CONE FLOW DISTANCE AT TANGENCY PT ----
C ----- SHARP CONE DISTANCE TO TANGENCY PT -----
       S1 - YT/SIN(TH*DTR)
C ----- COHEN CORRELATION -----
       RHOMUW-(0.225*(PE/PREF)**0.992)/
               (1.0-1.0213*(1.0-(HW/HREF)**0.3329))
       RHOMUW-RHOMUW*MUREF*RHREF
       NUW-RHOMUW/RHOW**2.
C ----- PSEUDO REYNOLDS NO. -----
       SQRE - SQRT(VE*S1/NUW)
C ----- BL THICKNESS AT TANG. PT - SHARP CONE, LAMINAR - N. NESS----
       DDS = (TE*S1/1.732/SQRE/TW)*(3.0*TW/TE + 2.01*
              (1.+(GAM-1.)*ME2/2.-TW/TE) - 1.62*(GAM-1.)*ME2/2.)
C ----- ADJUST FLOW DISTANCE FOR BLUNTNESS EFFECT -----
       FF- 1.
       DBL - DDELTAS + FF * DDS
       VENUW-SQRT(VE/NUW)
     SEFF = (1.732*VENUW*TW*DBL/TE)/(3.0*TW/TE + 2.01*
```

```
C ----- CALC BL MASS FLOW FOR LAMINAR CASE (LBM/S) ------
      MARKER - MARKER + 1
  51
       RHOMUW=(0.225*(PE/PREF)**0.992)/
              (1.0-1.0213*(1.0-(HW/HREF)**0.3329))
       RHOMUW-RHOMUW*MUREF*RHREF
       NUW-RHOMUW/RHOW**2.
      ME2 - ME * ME
C ----- B.L. MASS FLOW RATE -----
       SQRE-SQRT(VE*SEFF/NUW)
     MDOT = 2.*PI*RADIUS*VE*RHOE*SEFF*TE/1.732/SQRE/
              TW * (2.007*TW/TE + 2.01*(1.+(GAM-1.)*ME2/2.-TW/TE)
              -2.003 * (GAM-1.)*ME2/2.)
C ----- RADIUS OF FREE STREAM TO MATCH MDOT -----
  57 YS - SQRT(MDOT/PI/RHOO/VO)
C ----- SHARP CONE ATTACHED SHOCK ANGLE -----
     ETA = SQRT(1./MO**2.+(GAM+1.)*(SIN(TH*DTR))**2./2.)
     ETA - ASIN(ETA)*RAD
C ----- BOW SHOCK ANGLE (GAMMA) - BILLIG -----
     RM1 = 0.54/(MO-1.)**1.2
     RC = 1.143*RN*EXP(RM1)
     TANGAM - RC/YS * SQRT(1.+(YS*YS*(TAN(ETA*DTR)**2.)/RC**2.))
     GAMMA-RAD+ATAN (TANGAM)
2 -----PASS THRU BOW SHOCK -----
     VNORM - VO*SIN(GAMMA*DTR)
     VTAN - VO*COS (GAMMA*DTR)
     MNORM-VNORM/AO
     IF(IAIR.EQ.1)THEN
     CALL PGNS (MNORM, SSO, SS2, R2R1)
     ELSE
     CALL SHOCK (MNORM, VNORM, VTAN, RHOO, PO/144., HO, V2, SS2, R2R1, P2)
     ENDIF
C ----- CHECK FOR TURBULENCE -----
     IF(LAM.EQ.'YES') GO TO 64
     IF(IAIR.EQ.1)THEN
      CALL PAIR (PE, TE, HE, SS2, RHOE, AE, I1)
     ELSE
      CALL AIRTBL(PE/144 , TE, HE, SS2, RHOE, AE, WE, I1, N)
     ENDIF
     VE-SQRT(TGJ*(HTO-HE))
     DVE-VE-VE2
     AE-49.014*SQRT(TE)
     ME-VE/AE
C ----- COMPARE ENTROPY DOWNSTREAM OF SHOCK W/PREVIOUS BL ENTROPY -----
   64 IF(ABS(SS-SS2).GT.0.001)THEN
     IFLAG-IFLAG+1
      IF(IFLAG.LE 10)GO TO 49
      IFLAG1-IFLAG1+1
```

	WRITE(6,600)S GO TO 150
	600 FORMAT(//, 'STREAMLINE SWALLOWING FAILED', F5.4, 'FT FROM & NOSE DUE TO AN ENTROPY DISCONTINUITY')
C	SET ENTROPY PREVIOUS VALUE EQUAL TO CURRENT VALUE
	49 SS-SS2 IF(LAM.EQ.'NO')GO TO 74 GO TO 60 ELSE
	48 SS-SS2 VE1-VE2 VE2-VE
	IFIAG=0 IFIAG1=0
	IF(LAM.EQ.'NO')GO TO 99
С	LAMINAR BL THICKNESS - N. NESS
	DBL=(SEFF*TE/1.732/SQRE/TW)*(3.0*TW/TE + 2.01*(1.+(GAM-1.) & *ME2/2TW/TE)-1.62*(GAM-1.)*ME2/2.) DBL1=DBL2
	DBL2-DBL DDD-(SEFF*TE/1.732/SQRE/TW)*(0.993*TW/TE+0.383*(GAM-1.)*ME2/2.) DD1-DD2 DD2-DDD
	DM-0.383*SEFF*TE/1.732/SQRE/TW GO TO 99 ENDIF
С	TURBULENT STREAMLINE SWALLOWING
	63 MARKER-MARKER+1 IF(MMARKER.EQ.1) GO TO 61 MMARKER-1
	CALC INITIAL CONDITIONS
	BIGD - MDOT/2./PI/RADIUS/RHOE/VE
С	DISPLACEMENT THICKNESS
	DD - DBL-BIGD
С	MOM THICKNESS
	DM - RET*MUE/RHOE/VE
С	INITIAL ENTRAINMENT RATE
	F - ((DBL-DBL1)-(DDD-DD1))/DS
С	INITIAL VELOCITY CHANGE
	DVE - VE-VE1
С	INITIAL SHAPE PARAMETER
	H - DD/DM

C	STEP ENTRAINMENT EQ
	61 DBIGD - F*DS + (ME2-1.)*BIGD*DVE/VE
С	STEP MOMENTUM INTEGRAL EQ
	DDM = $CF*DS/2$ $(H+2ME2) * DM *DVE/VE$
С	NEW MASS FLOW THICKNESS
	BIGD - BIGD + DBIGD/2.25**.2
С	new momentum thickness
	DM = DM + DDM/2.25**.2
С	MODIFIED COMPRESSIBLE SHAPE PARAMETER
	H1 - BIGD/DM
С	TRANSFORMED COMPRESSIBLE SHAPE PARAMETER
	HBAR = 1. + (0.9/(H1-3.3))**0.75
С	KINEMATIC (INCOMP) SHAPE PARAMETER
	TERM1 = (HBAR+1.)*(HBAR-1.)**2. TERM2 = TERM1/HBAR/(3.*HBAR-1.)/(2.*HBAR-1.) TERM3 = R*ME2*TERM2/5. TERM4 = HBAR*(HBAR+1.) TERM5 = TERM4/(3.*HBAR-1.)/(2.*HBAR-1.) TERM6 = 1TERM5 TERM7 = R * ME2 * TERM6/5. TERM8 = 1. + TERM7 TERM9 = TERM3/TERM8 HK = HBAR * (1.+TERM9)
С	KINEMATIC MODIFIED SHAPE PARAMETER
	H1K = 3.4 + 1.87/(HK-0.5)**3.8
С	NEW ENTRAINMENT RATE
	F = 0.0306 * (H1K-3.0)**(653)
С	NEW SHAPE PARAMETER
	74 HR - HE + R*VE**2/TGJ IF(IAIR.EQ.1)THEN CALL PAIR(PW,TR,HR,JUNK,JUNK1,JUNK2,I2) ELSE CALL AIRTBL(PW/144.,TR,HR,JUNK,JUNK1,JUNK2,JUNK4,I2,N) ENDIF H-(TW/TE)*HBAR+TR/TE-1.
Ç	NEW DISP. THICKNESS
	DD-H*DM
С	NEW BL THICKNESS
	DBL=H1*DM+DD

C ----- INCOMPRESSIBLE TRANSFORMED REYNOLDS NO ------RETINC - (MUE/MST) * RET C ----- NEW SKIN FRICTION FROM INCOMP CORRELATION ----- $CFINC = 0.246 \times EXP(-1.56 \times HBAR) \times RETINC \times (-0.268)$ CF - (TE/TST) * CFINCC ----- MASS FLOW RATE ----MDOT = 2.*PI*RADIUS*VE*RHOE*BIGD GO TO 57 C-----REC FACTOR-----99 R = SORT(PR)IF (LAM.NE.'YES') R-PR**(1.0/3.0) C REC ENTH HR = HE + R*VE**2/TGJC-----ECKERT'S REFERENCE ENTHALPY-----HS = HE + 0.5*(HW-HE) + 0.22*(HR-HE)C----- REFERENCE CONDITIONS SST-0. IF(IAIR.EQ.1)THEN CALL PAIR(PW,TST,HS,SST,RHOST,AST,12) CALL AIRTBL(PW/144.0,TST,HS,SST,RHOST,AST,WST,I2 ,N) ENDIF C----- COHEN CORRELATIONS-----RMER =(0.225*(PE/PREF)**0.992)/1 (1.0 - 1.0213*(1.0 - ((HE+ 0.0)/HREF)**0.3329)) RMSR =(0.225*(PE/PREF)**0.992)/ 1 (1.0 - 1.0213*(1.0 - ((HS+ 0.0)/HREF)**0.3329)) RMS - RMSR*MUREF*RHREF RME - RMER*MUREF*RHREF MST - RMS/RHOST MUE - RME/RHOE IF(LAM.EQ.'NO')GO TO 12 IF(KKK.NE.0) GO TO 520 RMES - RME RMSS - RMS C STAG. PT. VELOCITY GRADIENT DUEDSS=(VO/2./RN)*(1.1+1.56/(1.+MO2)**.79) RMWR =(0.225*(PE/PREF)**0.992)/ 1 (1.0 - 1.0213*(1.0 - ((HW+ 0.0)/HREF)**0.3329))RMWS - RMWR*MUREF*RHREF C-----LEES STAG PT COLD WALL (540 R) Q-----QSTAGL=0.88*SQRT(RMSS*DUEDSS)*(HTO-128.7)

STAGD-17600.0*SQRT(RHOO/0.07647)*(VO/26000.0)**3.15/SQRT(RN) *((HTO-128.7)/HTO) QSTAGD-QSTAGD*(2.0**((DIM-1.0)/2.0)) *SQRT(DUEDS/DUEDSS) C------ FAY.RIDDELL STAG PT COLD WALL O -----OSTAGF=0.94*(RMWS**0.1)*(RMES**0.4)*SQRT(DUEDSS)*(HTO-128.7) QSTAGF-QSTAGF*(2.0**((DIM-1.0)/2.0))*SQRT(DUEDS/DUEDSS) C ----- STAG. PT. HEAT TRANSFER COEFF. -----RUCH1 - QSTAGL/(HTO-128.7) RUCHL-RUCH1 HRL- HR MRL-0.0 PEL-PE GO TO 102 520 RES - RHOE*VE*S/MUE FSX1-RHOE*VE*(MUE**0.25)*(SR**(1.25*DIM)) С С SX1 = SX1+(FSX1+FSX1L)*DS/2.0FSX1L-FSX1 C FSX = RMS*VE*(SR**(2.0*DIM))SX = SX+(FSX+FSXL)*DS/2.0FSXL-FSX FST=FSX*RME/RMS C ST - ST+(FST+FSTL)*DS/2.0FSTL-FST C-----LAMINAR FLOW-----C-----LEES EQUATION FOR HT. TRANSFER COEFF.-----RUCH1=QSTAGL*RMS*VE*SR**DIM/SQRT(RMSS*DUEDS *2.0*SX)/ 1 (2.0**(DIM/2.0))/(HTO-128.7) GO TO 102 C -----TURBULENT FLOW-----C----- SHARP CONE HT. XFER COEFF. NASA TECH PAPER 2345 JAN. 1985 --12 RUCH1 - 0.0296*2.25**.2*RHOST*VE/PR**0.667 1 /(RHOST*VE*S/MST)**0.20 C ----- COLD (ISOTHERMAL) WALL AND PSEUDO-HOT WALL HT. XFER -----102 QHW=RUCH1*(HR-HW) QCW=RUCH1*(HR-128.7) C-----PRINTOUTS-----IF(KKK.NE.O) GO TO 540 WRITE(6,900)TITLE WRITE(0,900)TITLE 900 FORMAT(1X,A62/) IF(GEO.EQ.'BLOG')WRITE(6,501)
901 FORMAT(3X,'BLUNTED OGIVE,AXISY-FLOW') IF(GEO.EQ.'CONE')WRITE(6,904) 904 FORMAT(3X, 'AXISYMMETRIC FLOW(CONE)') IF(GEO.EQ.'VK')WRITE(6,1506)
1506 FORMAT(3X,'VON KARMAN,AXISYM-FLOW') WRITE(6,909) 909 FORMAT(3X, 'LEES STAG POINT Q' WRITE(6,912) 912 FORMAT (3X, TURB Q VIA HOM. INTEGRAL EQ. USING 1/7TH POWER FOR VEL.

```
HOX-HO-128.7
C ----- WRITE TO OUTPUT FILE AND SCREEN ------
      WRITE(6,1014)
      WRITE(6,913)TIME.ALF.DELC.RN.RR.RG.XT.YT
      WRITE(0,913)TIME, ALF, DELC, RN, RR, RG, XY, YT
      IF(TYPE.EQ.'TEST')GO TO 817
      WRITE(6.1009)ZO.VO.MO.SSO.TTO.TO.PTO/2116.224.PO/2116.224.HTO.HO.
     &TW
      WRITE(0,1009)ZO, VO, MO, SSO, TTO, TO, PTO/2116.224, PO/2116.224, HTO, HO,
     UTA
      GO TO 818
  817 WRITE(6,1010)MO, VO, TTO, TO, PTO/2116.224, PO/2116.224, HTO, HO, TW, SSO
      WRITE(0,1010)MO, VO, TTO, TO, PTO/2116.224, PO/2116.224, HTO, HO, TW, SSO
  818 WRITE(6,1034)PTS/2116.224,SS2,TTS,R2R1,P2/2116.224
      WRITE(0,1034)PTS/2116,224,SS2,TTS,R2R1,P2/2116,224
 1014 FORMAT(1X, 'ENTHALPY - 0 AT 0 DEG R'/
     1 1X, 'COLD WALL Q BASED ON WALL TEMP OF 540 DEG R'/
     2 1X, 'HOT WALL Q BASED ON SUPPLIED WALL TEMP'//)
  913 FORMAT(
     3 1X, 'TIME (SEC)
                              ',F12.4/
     4 1X, 'RADOME GEOMETRY:'/
                  ANGLE OF ATTACK = ',F10.3/
CONE ANGLE (DEG) = ',F10.3/
NOSE RADIUS (FT) = ',F12.4/
     5 1X,
     6 1X,
     7 1X,'
     8 1X,
                  BASE RADIUS AT TANG. PT. (FT) - '.F12.4/
                  OGIVE RADIUS (FT) - ',F12.4/
     9 1X,
     1 1X,
                  COORDINATES OF NOSE/BODY TANG, PT. (FT) ARE X -', F5.5/
     2 1X.
                                                                     Y = ', F5.5/)
 1009 FORMAT(
     1 1X, 'FREE STREAM FLIGHT CONDITIONS: '/
     2 4X, ALTITUDE (FT) ',F12.4,2X, VELOCITY (FT/S)
                                                                        ',F12.4/
     3 4X. MACH NO.
                                    ,F12.4,2X, 'ENTROPY (BTU/LBM-R) ',F12.5/
     4 4X, ' TOT. TEMP (R)
                                  ',F12.4,2X,'STATIC TEMP (R)
                                                                        '.F12.4/
     4 4X, TOT. TEMP (R) ',F12.4,2X,'STATIC TEMP (R) ',F12.4/
5 4X,' TOT. PRESS (ATM) ',F12.4,2X,'STATIC PRESS (ATM) ',F12.4/
6 4X,' TOT. ENTH (BTU/LBM)',F12.4,2X,'STATIC ENTH (BTU/LBM)',F12.4/
     7 4X.' WALL TEMP (R)
                                   '.F12.4/)
 1010 FORMAT(
     1 1X, 'FREE STREAM TUNNEL CONDITIONS: '/
     2 4X, 'MACH NO. ',F12.4,2X,'VELOCITY (FT/S)
3 4X, 'TOT, TEMP (R) ',F12.4,2X,'STATIC TEMP (R)
                                                                        ',F12.4/
                                                                        ',F12.4/
     4 4X, TOT. PRESS (ATM) ',F12.4,2X, STATIC PRESS (ATM)
                                                                      ',F12.4/
     5 4X, TOT. ENTH(BTU/LBM) ',F12.4,2X, 'STATIC ENTH (BTU/LBM)',F12.4/6 4X, WALL TEMP (R) ',F12.4,2X, 'ENTROPY (BTU/LBM-R) ',F12.5/
     7)
 1034 FORMAT(
     1 1X. 'STAGNATION POINT CONDITIONS: '/
     2 4X, TOT. PRESS (ATM) ',F12.4,2X, 'ENTROPY (BTU/LBM-R) ',F12.5/
                                  ',F12.4/
     4 4X, TOT. TEMP (R)
     4 4X, DENSITY RATIO ACROSS NORMAL SHOCK (RHO2/RHO1)',8X,'',F12.4/
     5 4X, 'STATIC PRESS BEHIND NORMAL SHOCK (ATM)',8X,'
                                                                        '.F12.4/
      WRITE(6,611)
      WRITE(0,611)
      WRITE(6,914)QSTAGL,QSTAGF,QSTAGD
      WRITE(0,914)QSTAGL,QSTAGF,QSTAGD
      WRITE(0,926)
  611 FORMAT(2X, 'COLD WALL QSTAG FOR
                                             LEES
                                                      FAY-RIDDELL
                                                                        DETRA-'
     1, 'KEMP-RIDDELL(BTU/FT2-S)')
  914 FORMAT(21X, F8.2, 4X, F8.2, 10X, F8.2/)
```

```
FREEM(JSTEP, ISTEP) - MO
      EDGEMR(JSTEP, ISTEP) - ME/MO
      EDGEPR(JSTEP, ISTEP) - PE/PO
      ISTEP - ISTEP + 1
      ENDIF
C ---- PRINT COLUMN HEADING IN OUTPUT FILE EVERY 40TH WRITE STEP-
  724 IF(KKK.EQ.O.OR.MOD(KKK,NOUT*40).EQ.0)GO TO 560
      GO TO 570
  560 IF(KKK.NE.O ) WRITE(6,918)
  918 FORMAT(1H1)
     WRITE(6,915)
  915 FORMAT( 54H S/RN
                        X/RN Y/RN RAD/RN TH PE/PO
                                                           ME/MO
                                                                  VE ,
                        HE/HTO
                                                           RUCH ,
             48H SS
                               RES
                                       RET
                                                 DBL
    1
                                  QHW
                           QCW
                                           LAM )
                   HR
    2
             31H
                              PE/PO
                                      ME TE/TTS
                                                    RUCH HR .
  926 FORMAT( 45H
                  S/RN
                    QCW/QS LAM )
    1
             17H
  ..... WRITE TO OUTPUT FILE WHEN REMAINDER(NOUT/KKK) = 0 .....
  570 IF(MOD(KKK, NOUT).EQ. 0. OR. KKK.EQ. 0) GO TO 580
     GO TO 590
C 580 HEX-HE-128.7
     HRX-HR-128.7
  580 CP=64.4*(PE-PO)/(RHOO*VO**2.)
      ST-QHW/RHOE/VE/(HR-HW)
     IF(GEO.EQ.'VK'.AND.S.GE.(STN+.04134))THEN
     WRITE(6,916)
     1S/RN, XXX2/RN, YYY2/RN, RADIUS/RN, TH, PE/PO, ME/MO, VE, SS, HE/HTO,
     2RES, RET, DBL, RUCH1, HR, QCW, QHW, ST, LAM
     ELSE
     WRITE(6,916)
     1S/RN, X/RN, Y/RN, RADIUS/RN, TH, PE/PO, ME/MO, VE, SS, HE/HTO.
     2RES, RET, DBL, RUCH1, HR, QCW, QHW, ST, LAM
  916 FORMAT(1X,2F7.2,2F6.2,F6.1,2F7.3,F7.0,F7.4,F7.3,2(1PE9.2),E10.3,
           OPF8.5.F8.1.2F9.3.E12.4.2X.A3)
C ---- TURBULENT DEBUG WRITE -----
     WRITE(6,955)
C 955 FORMAT( 52H S/RN
                        PE/PO
                                VE
                                      BIGD
                                                    HBAR
                                                                MDOT.
С
    1
             49H
                        DM
                                   DBL
                                                            Н
C
             12H
                        H1 )
С
     WRITE(6,956)
    1S/RN, PE/PO, VE, BIGD, HBAR, MDOT, DM, DBL, F, H, H1
C
C 956 FORMAT(1X,2F6.2,F7.0,8E12.3)
C----FOR PLOT FILE-----
      IF(GEO.EQ.'VK'.AND.S.GE.(STN+.04134))THEN
     WRITE(8,916)
     1S/RN, XXX2/RN, YYY2/RN, RADIUS/RN, TH, PE/PO, ME/MO, VE, SS, HE/HTO,
     2RES, RET, DBL, RUCH1, HR, QCW, QHW, ST, LAM
     ELSE
     WRITE(8,916)
     1S/RN, X/RN, Y/RN, RADIUS/RN, TH, PE/PO, ME/MO, VE, SS, HE/HTO.
     2RES, RET, DBL, RUCH1, HR, QCW, QHW, ST, LAM
     ENDIF
C ----- FOR PRINT TO SCREEN -----
```

```
C-----INTERPOLATION FOR RUCH & HR-----
 550 IF(MOD(KKK, NOUT).EQ.0)GO TO 551
     HEX-HE-128.7
     HRX-HR-128.7
 551 C = (XLEN(IX)-SL)/(S-SL)
     PEX-PEL+C*(PE-PEL)
     RUC(IX) = RUCHL +C*(RUCH1-RUCHL)
     HRT(IX) = HRL + C*(HR-HRL)
     MRX=MRL+C*(ME-MRL)
C ----- WRITE TO SCREEN -----
     WRITE(0,930)
    1S/RN, PE/PO, ME, TE/TTS, RUCH1, HR, QCW/QSTAGL, LAM
 930 FORMAT(1X,F8.2,F9.2,F7.2,F6.2,F9.5,F7.1,F6.2,4X,A3)
C ----- STEP STATION FOR WALL TEMP -----
     IX - IX+1
105 KKK - KKK+1
     RUCHL - RUCH1
     PEL-PE
     HRL - HR
     MRL-ME
     IF(S + DS.LT.SMAX)GO TO 100
     DS - SMAX-S
     IF(DS.GT.0.0) GO TO 100
     LAM - 'YES'
 150 RETURN
     END
     SUBROUTINE SCONE (GAM. PC. MI. DEL. PO)
     REAL*4 MI2, MI4, MI6, MI
     DTR-1.0/57.3
     GAM - 1.4
     MI2 - MI*MI
C /* SHARP CONE PRESSURE (SIMON & WALTER , AIAA JR., V.1,\#7 ) */
     SD2 - SIN(DEL*DTR)**2
     MI4 - MI2*MI2
     MI6 - MI4*MI2
     GP7 - GAM+7.0
     F1 = GP7/4.0 - (GAM-1.0)**2/16.0 + 6.0/MI6 +
    1 (MI2-1.0)/MI4/SIN(DEL*DTR)
     CPC-F1*SD2
     PCO = 1.0 + GAM+MI2*CPC/2.0
     PC - PCO*PO
     RETURN
     SUBROUTINE BCONE(PE.PC.DEL.RN.X,S.MO)
C /* BLUNTED CONE PRESSURES, (BLICK & FRANCIS, AIAA JR., V.4,#3) */
     REAL*4 MO,NX
     PI-3.14
     SP = X*(DEL*PI/180.0)**2/RN
     IF (SP.GT.O.106)GO TO 40
     NX = -0.308*(LOG(SP) + 2.24)
     PE =(0.929*(MO/2.8)**NX)*PC
     GO TO 100
  40 CONTINUE
     IF(SP.LE.O.106) GO TO 90
     IF(SP.GE.1.06) GO TO 90
     NX=-0.116*SQRT(MO-2.8)*SIN((LOG(SP)+2.24)/0.731)
     PE = PC*(SP**0.032)*EXP(NX)
     GO TO 100
 90 PE - PC
100 RETURN
     END
```

```
SUBRCUTINE PRMY(GAM, PE, DTX, M, P)
C /* PRANDTL MEYER TURNING P-F(DTHETA), NACA1135, EQ(174)
      FOR SMALL TURNING ANGLES
      REAL*4 M, M2, M4, M6, M2M1
С
      GAM-1.4
     M2-M*M
      M4-M2*M2
      M6-M2*M4
      GP1=GAM+1.0
      M2M1-M2-1.0
      DT-DTX*3.14/180 ·
      PR-1.0-GAM*M2*DT, SQRT(M2M1)
           +GAM*M2*(GP1*M4-4.0*M2M1)*DT*DT/(4.0*M2M1**2)
           -(GAM*M2*DT**3/2.0/M2M1**3.5)*
           (GP1*M4**2/6.0-(5.0+7.0*GAM-2.0*GAM**2)*M6/6.0
            +5.0*GP1*M4/3.0-2.0*M2+4.0/3.0)
     4
     PE-PR*P
      RETURN
      END
      SUBROUTINE XMACH(GAM, M, PPT)
   /* MACH FUNCTION, M-F(P/PTOTAL) NACA1135, EQ(44) */
     REAL*4 M
      GAM-1.4
      3M1-GAM-1.0
      M-SQRT((PPT**(-GM1/GAM)-1.0)*2.0/GM1)
      RETURN
      DO 100,I - 2,N
      IF(X.LE.XLIST(I)) GO TO 200
  100 CONTINUE
      I - N
  200 F-FLIST(I-1)+(X-XLIST(I-1))*(FLIST(I)-FLIST(I-1))/
     1 (XLIST(I)-XLIST(I-1))
     RETURN
      END
     SUBROUTINE PGNS (M1, SS1, SS2, RHOR1)
C ---- PERFECT GAS - NORMAL SHOCK SUBROUTINE
     REAL*4 M1,M12
      M12-M1*M1
      P2OP1=1. + 2.8/2.4 * (M12 - 1.)
      R2OR1 = 2.4 * M12 / (2.+.4*M12)
      T2OT1-P2OP1/R2OR1
      CP-.24
     R-.068554
      SS2=SS1+CP*ALOG(T2OT1)-R*ALOG(P2OP1)
     RETURN
     END
     SUBROUTINE PAIR(P,T,H,SS,RHO,A,I)
C ------ PERFECT GAS AIR RELATIONS -----
     PREF-2116.224
     TREF-537.
     SREF-0.59945
     CP-.24
     R1-53.34
     R2=.068554
     GOTO(10,20,40,40,50)I
  10 T=TREF*EXP((SS-SREF+R2*ALOG(P/PREF))/CP)
     H-CP*T
     GO TO 60
  20 T-H/CP
      SS=CP*ALOG(T/TREF)-R2*ALOG(P/PREF)+SREF
     GO TO 60
  40 SS=SREF+CP*ALOG(T/TREF)-R2*ALOG(P/PREF)
     H-CP*T
     GO TO 60
  50 T-H/CP
     P=PREF*EXP((CP*ALOG(T/TREF)-SS+SREF)/R2)
```

```
60 RHO-P/R1/T
      A-4°.014*SQRT(T)
      RETURN
      END
C ---- REAL GAS SUBROUTINE TO PASS THROUGH A NORMAL OR OBLIQUE
C ---- SHOCK GIVEN PROPERTIES ON UPSTREAM SIDE
      SUBROUTINE SHOCK (MNORM, VNORM, VTAN, RHO1, P1, H1, V2, SS2, R2R1, P2P)
     REAL MNORM, VNORM, VTAN, RHO1, P1, H1
      R2R1-6.*MNORM**2./(MNORM**2.+5.)
     R2-R2R1*RHO1
      ERR-100.
      DO 10 i=1,50
      P2-P1+RH01*VNORM**2.*(1.-1./R2R1)*2.1584E-4
     H2-H1+VNORM**2./2.*(1.-1./R2R1**2.)/25051.6
     PP-P2
     HP-H2
     N-0
     SS2-0.
     12-2
      CALL AIRTBL(PP,T2,HP,SS2,RHOP,A2,W2,I2,N)
     RHO2-RHOP
      ERR-ABS((RHO2-R2)/RHO2)
      IF(ERR.LT.1.0E-4) GO TO 11
     R2-RH02
     R2R1-RH02/RH01
  10 CONTINUE
  11 CONTINUE
     V2N-VNORM/R2R1
     V2=SQRT(V2N**2.+VTAN**2.)
     P2P-P2*144.
      RETURN
     FND
      SUBROUTINE SNUGS (PC, TR, I)
      DIMENSION PC(3),TR(3),A(2)
      PC(3) = PC(1) + (1.0-TR(1))*(PC(2)-PC(1))/(TR(2)-TR(1))
     A(1) - ABS(TR(1)-1.0)
     A(2) = ABS(TR(2)-1.0)
      TMAX - MAX (A(1),A(2))
     DO 100 I = 1.2
     IF (TMAX.EQ.A(I))GO TO 9
 100 CONTINUE
    9 PC(I) - PC(3)
     RETURN
```

END

APPENDIX B

ABBOHT VARIABLE DEFINITIONS

AE	speed of sound at BL edge (ft/s)
ALF	angle of attack (deg)
ALT	altitude (ft)
AO	free-stream speed of sound (ft/s)
AS	speed of sound at stagnation point (ft/s)
AST	speed of sound at Eckert's reference enthalpy (ft/s)
AW	speed of sound at wall (ft/s)
BETA	velocity gradient (ft/s-ft)
BIGD	mass flow thickness (ft)
CF	compressible skin friction coefficient
CFINC	incompressible skin friction coefficient
CONV	convergence identifier
CP	pressure coefficient
CPO	specific heat of air at constant pressure (Btu/lbm-°F)
DBIGD	mass flow thickness change (ft)
DBL	BL thickness (ft)
DBL1,2	stored values of BL thickness (ft)
DD	displacement thickness (ft)
DD1,2	stored values of BL displacement thickness (ft)
DDD	BL displacement thickness (ft)
DDELTAS	stagnation point BL thickness (ft)
DDM	momentum thickness change (ft)
DDS	BL thickness at nose/body tangency point (ft)
DEL	incident angle at nose/body tangency point (deg)
DELC	cone half angle (deg)
DELT	change in incidence angle (deg)
DELTA	body angle at nose/body tangency point (deg)
DIM	geometry identifier
DM	momentum thickness (ft)
DS	surface distance step (ft)
DTR	degrees to radian factor (0.01745)
DUI	free-stream stagnation density (lbm/ft ³)
DU2	dummy variable
DU3	dummy variable
DUEDS	velocity gradient (ft/s-ft)
DUEDSS	velocity gradient at stagnation point (ft/s-ft)
DVE	velocity change (ft/s)
DXXX	change in x coordinate of body surface for von Karman
	radome shape at angle of attack (ft)
DYYY	change in y coordinate of body surface for von Karman
	radome shape at angle of attack (ft)
EDGEMR	BL edge Mach no./free-stream Mach no.
EDGEPR	BL edge pressure/free-stream pressure
ETA	sharp cone-attached shock angle (deg)
F	entrainment rate (ft/s-ft)
FF	scale factor (currently 1.0)
FREEM	free-stream Mach no.

FSX RMS*VE*Y²

GAM ratio of specific heats
GAMMA bow shock angle (deg)
GEO geometry identifier

H compressible conventional shape parameter (DD/DM)
H1 compressible modified shape parameter (BIGD/DM)

H1K incompressible modified shape parameter

HBAR transformed shape parameter

HE BL edge enthalpy based on 0°R (Btu/lbm)

HEX BL edge enthalpy based on 540°R (Btu/lbm)

HK incompressible conventional shape parameter

HO free-stream static enthalpy based on 0°R (Btu/lbm)

HR recovery enthalpy based on 0°R (Btu/lbm)

HREF reference enthalpy for Cohen correlation (8465 Btu/lbm)
HRL last (previous) recovery enthalpy based on 0°R (Btu/lbm)

HRT recovery enthalpy based on 0°R (Btu/lbm)
HRX recovery enthalpy based on 540°R (Btu/lbm)

HS Eckert's reference enulalpy based on 0°R (Btu/lbm)

HTO total enthalpy based on 0°R (Btu/lbm)
HTX total enthalpy based on 540°R (Btu/lbm)
HW wall enthalpy based on 0°R (Btu/lbm)

I dummy indexing variable

I1-I5 1-5

IAIR switch between perfect and equilibrium air properties
IFLAG no. of laminar streamline swallowing iterations to converge
IFLAG1 no. of times laminar streamline swallowing iterations have

been hung up in loop at a discontinuity

IGE geometry specification variable

IQS currently not used

ISTEP indexes for each flow station ITR transition criterion index ITY initial condition index

IX index for each change in NPTS
J dummy indexing variable
JSTEP steps for each flow case
JUNK,1,2,4 dummy variables

KKK equals zero for first iteration

LAM laminar BL identifier

LT length of radome to tangency point (ft)

MACH Mach no.

MARKER steps for each marching step
MDOT mass flow rate (lbm/s)
ME Mach no, at BL edge

ME2 Mach no, at BL edge squared

MMARKER equals 1 to initialize turbulent swallowing equations

MNORM free-stream Mach no. normal to bow shock

MO free-stream Mach no.

MO2 free-stream Mach no. squared
MRL last (previous) BL edge Mach no.
MRX interpolated Mach no. at BL edge

MST viscosity at Eckert's reference enthalpy (lbm/ft-s)

MUE viscosity at BL edge (lbm/ft-s)

MUREF reference viscosity for Cohen correlation (1.15312E-5 lbm/ft²-s)

LAUREL, MARYLAND

MUS viscosity at stagnation point (lbm/ft-s)

NOUT output to print and plot files every NOUT step
NPTS number of stations wall temperature will be specified

NUE kinematic viscosity at BL edge (ft²/s) NURL switch for creating output files NUW kinematic viscosity at wall (ft²/s)

P pressure (lbf/ft²)
PC surface pressure (lbf/ft²)
PE pressure at BL edge (lbf/ft²)

PEL last (previous) BL edge pressure (lbf/ft²)
PEX interpolated pressure at BL edge (lbf/ft²)

PI 3.14159

PO free-stream static pressure (lbf/ft²)

PR Prandtl no.

PREF conversion factor from atm to psf (2116.224 lbf/ft²)

PTO free-stream total pressure (lbf/ft²)

PTS pressure at stagnation point (lbf/ft²)

PW static pressure at wall (lbf/ft²)

Q heat transfer rate (Btu/ft²-s)

QCW cold wall heat transfer rate based on wall temperature of

540°R (Btu/ft²-s)

QHW hot wall heat transfer rate (Btu/ft²-s)

QSTAGD Detra, Kemp, Riddell stagnation point heat transfer rate

(Btu/ft²-s)

QSTAGF Fay-Riddell stagnation point heat transfer rate (Btu/ft²-s) QSTAGL Lees's stagnation point heat transfer rate (Btu/ft²-s)

R recovery factor RAD 1 radian = 57.3

RADIUS radius of body in body coordinate system (ft)

RC term in equation for bow shock angle
RES Reynolds no. based on surface distance
RET Reynolds no. based on momentum thickness

RETING incompressible Reynolds no.

RG radius of ogive (ft)

RHOE density at BL edge (lbm/ft³)

RHOMUE density × viscosity at BL edge (lbm²/ft⁴-s)
RHOMUW density × viscosity at wall (lbm²/ft⁴-s)

RHOO free-stream density (lbm/ft³) RHOS stagnation point density (lbm/ft³)

RHOST density at Eckert's reference enthalpy (lbm/ft³)

RHOW density at wall (lbm/ft³)

RHREF reference density for Cohen correlation (0.0803707

lbm/ft³)

RM1 term in equation for bow shock angle density × viscosity at BL edge (lbm²/ft⁴-s)

RMER dummy variable

RMES RME at stagnation point (lbm²/ft⁴-s)

RMS density × viscosity at Eckert's reference enthalpy

 (lbm^2/ft^4-s)

RMSR dummy variable

RMSS RMS at stagnation point (lbm²/ft⁴-s)

RMWR dummy variable

RMWS density \times viscosity at wall at stagnation point (lbm²/ft⁴-s)

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RN nose radius (ft)

RR radius of radome base at tangency point (ft)

RRR y coordinate of radome base including angle of attack (ft)

RUC interpolated heat transfer coefficient (lbm/ft²-s)

RUCH1 heat transfer coefficient (lbm/ft²-s)

RUCHL last (previous) heat transfer coefficient (lbm/ft²-s)

S surface distance (ft)

S1 sharp cone distance to tangency point (ft)
SEFF effective sharp cone surface distance (ft)
SL last (previous) surface distance (ft)
SMAX maximum surface distance (ft)
SO initial surface distance (ft)

SR y coordinate of body in free-stream coordinate system (ft)
SRTP y coordinate of nose/body tangency point in free-stream

square root of VE >: S1/NUW

coordinate system (ft)

SS entropy at BL edge (Btu/lbm-°R)
SSO free-stream entropy (Btu/lbm-°R)
SS2 entropy at stagnation point (Btu/lbm-°R)

entropy at Eckert's reference enthalpy (Btu/lbm-*R)

SSW entropy at wall (Btu/lbm-°R)
STA wall temperature (*R)

STN surface distance to nose/body tangency point (ft)

STRAN transition Reynolds no.
TANGAM tangent of GAMMA
TDUM dummy variable

TE BL edge temperature (°R)

TERM1-9 terms in shape factor conversion equations

TGJ $50,063 \text{ (lbm-ft}^2/\text{Btu-s}^2\text{)}$

TH body incidence angle to flow (deg)

TH1 body slope at nose/body tangency point with respect to

free-stream (deg)

THL last (previous) incidence angle (deg)

TI time (s)
TIME time (s)

TO free-stream static temperature (°R)

TOO total temperature (°R)
TR recovery temperature (°R)
TRAN specifies transition correlation

TST temperature at Eckert's reference enthalpy (°R)

TTO free-stream total temperature (°R)
TTS stagnation point temperature (°R)

TURB turbulent BL identifier

TYPE specifies format of input conditions V2 velocity immediately behind shock (ft/s)

VE velocity at BL edge (ft/s)
VE1,2 saved BL edge velocities (ft/s)

VENUW VE \times NUW (ft³/s²)

VNORM free-stream velocity normal to bow shock (ft/s)

VO free-stream velocity (ft/s)

VTAN free-stream velocity tangential to bow shock (ft/s)
WE molecular weight at BL edge (lbm/lbm-mol)
WO free-stream molecular weight (lbm/lbm-mol)

**

WS	molecular weight at stagnation point (lbm/lbm-mol)
WST	molecular weight at Eckert's reference enthalpy (lbm/lbm-mol)
WW	molecular weight of gas at wall (lbm/lbm-mol)
X	x coordinate of body in free-stream coordinate system (ft)
XLEN	surface distance (ft)
XT	x coordinate of nose/body tangency point at angle of attack in free-stream coordinate system (ft)
XTC	surface x coordinate in body coordinate system at nose/ body tangency point (ft)
XXX1,2	x coordinate of body surface for von Karman radome shape at angle of attack (ft)
Y	y coordinate of body in free-stream coordinate system (ft)
YS	raclius of free-stream stream tube required to match MDOT (ft)
YT	y coordinate of nose/body tangency point at angle of at- tack in free-stream coordinate system (ft)
YTC	surface radius in body coordinate system at nose/body tangency point (ft)
YYY1,2	y coordinate of body surface for von Karman radome shape at angle of attack (ft)
ZO	altitude (ft)

GLOSSARY

c_f - skin friction T - temperature F - entrainment parameter TT - total temperature h - enthalpy TW - wall temperature H - conventional form parameter (δ^*/θ) u - velocity H_1 - modified form parameter $(\delta - \delta^*/\theta)$ u - radius from centerline u - velocity gradient (du_e/ds) - ratio of specific heats (c_p/c_v) m - boundary layer mass flow rate g - velocity gradient (du_e/ds) - ratio of specific heats (c_p/c_v) M - Mach no. g - boundary layer thickness P - pressure g - boundary layer displacement thickness P - Prandtl no mass flow thickness P - heat transfer rate g - mass flow thickness Q - stagnation point heat transfer rate g - boundary layer momentum thickness P - radius g - boundary layer momentum thickness P - radius g - bow shock angle P - viscosity- kinematic viscosity
h - enthalpy TW - wall temperature H - conventional form parameter (δ^*/θ) u - velocity x - longitudinal coordinate H_1 - modified form parameter $(\delta - \delta^*/\theta)$ v - radius from centerline v - radius from centerline m - boundary layer mass flow rate v - ratio of specific heats v - ratio of specific heats v m - Mach no. v - boundary layer thickness v - pressure v - boundary layer displacement thickness v - heat transfer rate v - mass flow thickness v - sharp cone-attached shock angle v - sharp cone-attached shock angle v - boundary layer momentum thickness v - boundary layer momentum thickness v - bow shock angle v - viscosity
$H - conventional form parameter (\delta^*/\theta) x - longitudinal coordinate H_1 - modified form parameter (\delta - \delta^*/\theta) \alpha - longitudinal coordinate H_1 - modified form parameter (\delta - \delta^*/\theta) \alpha - longitudinal coordinate H_1 - modified form parameter (\delta - \delta^*/\theta) \alpha - longitudinal coordinate H_1 - modified form parameter (\delta - \delta^*/\theta) \alpha - longitudinal coordinate H_2 - longitudinal coordinate (\delta - \delta^*/\theta) \alpha - longitudinal coordinate H_2 - longitudinal coordinate (\delta - \delta^*/\theta) \alpha $
parameter (δ^*/θ) x - longitudinal coordinate H_1 - modified form parameter $(\delta - \delta^*/\theta)$ α - angle of attack m - boundary layer mass flow β - velocity gradient (du_e/ds)
H_1 — modified form parameter $(\delta - \delta^*/\theta)$ — angle of attack m — boundary layer mass flow β — velocity gradient (du_e/ds) — rate γ — ratio of specific heats (c_p/c_v) M — Mach no. δ — boundary layer thickness P — pressure δ^* — boundary layer displacement thickness O — mass flow thickness O — mass flow thickness O — mass flow thickness O — stagnation point heat transfer rate O — stagnation point heat transfer rate O — boundary layer momentum O — boundary layer momentum thickness O — boundary layer momentum thickness O — boundary layer momentum O — boundary l
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
m — boundary layer mass flow rate γ — ratio of specific heats (c_p/c_v) γ — ratio of specific heats (c_p/c_v) γ — ratio of specific heats (c_p/c_v) γ — boundary layer thickness γ — boundary layer displacement thickness γ — boundary layer displacement thickness γ — mass flow thickness γ — sharp cone-attached shock angle γ — radius of body at γ — boundary layer momentum thickness γ — boundary layer momentum thickness γ — boundary layer momentum thickness γ — bow shock angle γ — viscosity
rate γ - ratio of specific heats (c_p/c_v) M - Mach no. δ - boundary layer thickness P - pressure P - Prandtl no. P - total pressure Q - heat transfer rate Q - stagnation point heat transfer rate P - radius of body at P - radius
M — Mach no. δ — boundary layer thickness P — pressure P — Prandtl no. P — total pressure P — heat transfer rate P — heat transfer rate P — sharp cone-attached shock angle P — radius of body at P — boundary layer momentum thickness P — boundary layer displacement thickness P — boundary layer displacement thickness P — sharp cone-attached shock angle P — boundary layer displacement thickness P — boundary layer displacement thickness P — sharp cone-attached shock angle P — boundary layer displacement thickness P — sharp cone-attached shock angle P — boundary layer momentum thickness P — boundary laye
P - pressure P - pressure P - Prandtl no. P - total pressure P - heat transfer rate P - stagnation point heat transfer rate P - total pressure P - sharp cone-attached shock angle P - boundary layer momentum thickness P - radius of body at P - boundary layer momentum thickness P - radius P - bow shock angle P - bow shock angle P - viscosity
Pr Prandtl no.thickness PT total pressure Δ mass flow thickness q heat transfer rate η sharp cone-attached shock QS stagnation point heat transfer rate θ boundary layer momentum r radius of body at S λ bow shock angle R radius λ bow shock angle Re Reynolds no. μ viscosity
PT — total pressure Δ — mass flow thickness q — heat transfer rate η — sharp cone-attached shock QS — stagnation point heat transfer rate θ — boundary layer momentum r — radius of body at S θ — bow shock angle R — radius θ — bow shock angle Re — Reynolds no. θ — viscosity
q - heat transfer rate η - sharp cone-attached shock angle θ - boundary layer momentum θ - radius θ - bow shock angle θ - bow shock angle θ - viscosity
QS - stagnation point heat transfer rate θ - boundary layer momentum r - radius of body at S thickness R - radius λ - bow shock angle Re - Reynolds no. μ - viscosity
QS - stagnation point heat transfer rate θ - boundary layer momentum thickness R - radius λ - bow shock angle Re - Reynolds no. μ - viscosity
fer rate θ - boundary layer momentum r - radius of body at S thickness R - radius λ - bow shock angle Re - Reynolds no. μ - viscosity
r - radius of body at S thickness R - radius λ - bow shock angle Re - Reynolds no. μ - viscosity
R - radius λ - bow shock angle Re - Reynolds no. μ - viscosity
Re - Reynolds no. μ - viscosity
nation point ρ – density
s_{ij} - function defined in Ref. 26 σ - cone incident angle to flow

Subscripts

e n r	 sharp cone boundary layer edge blunted nose recovery stagnation point 	sh ₩ *	 shock wall Eckert's reference temperature free stream
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